

Semantics for Hybrid Components

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An overview of categorical constructions for interpreting hybrid components via

- Coalgebra
- (Elgot) Monads



Iteration

Components

Standalone computational units, typically with an internal state, that interact with environment

Hybrid Components

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Standalone computational units, typically with an internal state, that interact with environment

Hybrid Components

If a component's environment contains physical processes (e.g. velocity, time) we qualify the component as **hybrid**



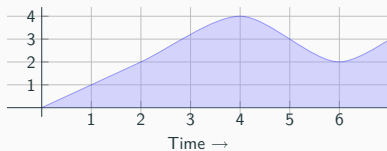
to emphasise the discrete-continuous interaction

The Essence of Hybrid Components



Described via classical methods of computation

+



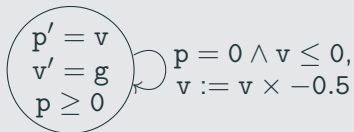
Described via differential equations

Often found in the form of

- cruise-controllers, thermostats, medical devices, ...
- **impact-based** physical systems

Formalisms for Hybrid Components

Hybrid Automata



Hybrid (Component-based) Programming

```
while true do { if b then heatReactor()
                else coolReactor() }
```

We will provide semantics to the two formalisms

- first for hybrid automata
- then for hybrid component-based programming

Hybrid Automata and its Variants

Hybrid automata: standard formalism for modelling hybrid systems

Underlying notion has several variants

- deterministic
- non-deterministic
- probabilistic
- reactive
- weighted
- ...


To be formally detailed later on

Unfortunately: no **uniform semantics** for hybrid automata

Coalgebra is a uniform theory of **state-based transition** systems

We use it to tackle the propounded issue, and obtain uniformly

- semantics
- a notion of bisimulation
- a notion of observational behaviour
- and a regular-expression-like language

Hybrid Iteration

Suitable semantics for **hybrid iteration** is difficult to establish

Previous work crucially relies on nondeterminism and gives rise to problematic equations, e.g.

$$\text{while true do } \{ p \} = 0$$

Alternative (deterministic) semantics via final coalgebra + weak bisimilarity. It revolves around two monads for hybrid computation

$$\hat{H} \xrightarrow{\text{intensional to extensional}} H$$


Abstracts away intermediate computational steps

Hybrid Iteration + Internal State

We take a monad able to handle internal states in programming

Then **combine** it with the extensional hybrid monad, and show that the new monad supports iteration. This yields ...

an interpretation domain for hybrid components in programming

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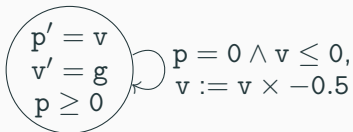
Hybrid Components

Conclusions and Future Work

The Essence of Hybrid Automata

They extend **non-deterministic** finite automata with

- differential equations (for describing continuous dynamics)
- location invariants (for restricting the latter)
- assignments (for describing discrete dynamics)
- guards (for restricting the latter)



Hybrid Automata Formally

Hybrid automaton is a tuple $(L, E, X, dyn, inv, asg, grd)$ where

- L is a finite set of locations, E is a transition relation $E \subseteq L \times L$, X is a finite set of **real-valued variables**
- dyn is a function that associates to each location a system of **differential equations** over X
- inv is a function that associates to each location its **invariant** (a predicate over the variables in X)
- asg is a function that given an edge it returns an **assignment** command over X
- grd is a function that given an edge it returns a **guard** (*i.e.* a predicate over the variables in X)

Definition (Coalgebra)

A function $X \rightarrow FX$ where $F : \text{Set} \rightarrow \text{Set}$ is a **functor**

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Different F , different transition systems

- $X \rightarrow \text{Id}X$ (deterministic)
- $X \rightarrow P_\omega X$ (non-deterministic)
- $X \rightarrow P_\omega(A \times X)$ (labelled non-deterministic)
- $X \rightarrow D_\omega X$ (probabilistic)
- ...

The Message of Coalgebra

Coalgebra serves as a uniform theory of transition systems, whose level of abstraction is functoriality

It includes,

- notions of (bi)simulation and observational behaviour
- techniques for minimisation
- notions of regular-expression
- ...

A Surprisingly Useful Remark

Hybrid automata are nothing more than classical, non-deterministic automata with **decorated** states and edges, i.e.

$$L \rightarrow P_{\omega}(L \times \text{Asg} \times \text{Grd}) \times \text{DifEq} \times \text{Inv}$$

This immediately provides

- a uniform notion of hybrid automata,
- a uniform notion of (bi)simulation and regular-expression



More details in [Neves and Barbosa, 2017]

A Zoo of Hybrid Automata

$$L \rightarrow F(L \times \text{Asg} \times \text{Grd}) \times \text{DifEq} \times \text{Inv}$$

Functor	Type
Id	Deterministic
P_ω	Classical
D_ω	Markov
$P_\omega D_\omega$	Probabilistic
W_ω	Weighted

Uniform Semantics for Hybrid Automata

Many variants of hybrid automata come equipped with a semantics

We can encode these uniformly as a functor

$\llbracket - \rrbracket : \text{HybAt}(F) \longrightarrow \text{A Category of Coalgebras}$



Transition systems involving sols. of diff. eqs.

Three assumptions (last two used merely to simplify presentation)

Unique Solutions

The function `dyn` only outputs systems of differential equations with **exactly one solution**. This induces a function

$$\text{flow} : L \times \mathbb{R}^n \times [0, \infty) \rightarrow \mathbb{R}^n$$

Urgent Transitions

As soon as an edge is enabled the current location must switch

No Invariants

The invariants of all locations are true

The Semantics

$$L \times \mathbb{R}^n \rightarrow F(L \times \text{Asg} \times \text{Grd}) \times \text{DifEq}$$

$$\Rightarrow L \times \mathbb{R}^n \rightarrow F(L \times \text{Asg} \times \text{Grd}) \times (\mathbb{R}^n)^{[0,\infty)} \rightarrow \text{Space of continuous trajectories}$$

$$\Rightarrow L \times \mathbb{R}^n \rightarrow F\left(L \times \text{Asg} \times \text{Grd} \times (\mathbb{R}^n)^{[0,\infty)}\right) \rightarrow \text{Tensorial strength}$$

$$\Rightarrow L \times \mathbb{R}^n \rightarrow F\left(L \times \text{Asg} \times \coprod_{d \in [0,\infty)} (\mathbb{R}^n)^{[0,d)} \times \mathbb{R}^n + (\mathbb{R}^n)^{[0,\infty)}\right)$$

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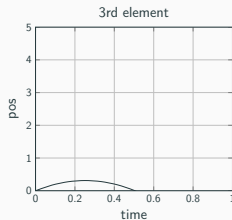
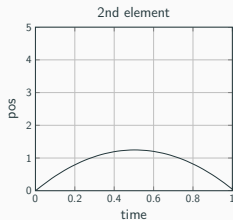
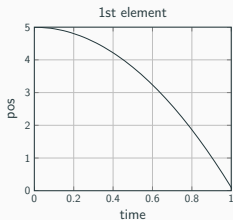
We obtain a coalgebra for $F\left(- \times \coprod_{d \in [0,\infty)} (\mathbb{R}^n)^{[0,d)} + (\mathbb{R}^n)^{[0,\infty)}\right)$

Revisiting the Bouncing Ball ($F = \text{Id}$)

Via the semantics functor $\llbracket - \rrbracket$ we obtain the following picture

$$\text{bb} = \left\{ \begin{array}{l} p' = v \\ v' = g \\ p \geq 0 \end{array} \right\} \begin{array}{l} p = 0 \wedge v \leq 0, \\ v := v \times -0.5 \end{array}$$

$\text{beh}_{\llbracket \text{bb} \rrbracket}(*, (5, 0)) = \dots$
↓
Position and velocity



Our generalised semantics covers the established semantics for

- deterministic
- non-deterministic
- and probabilistic hybrid automata

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We have an analogous result for (bi)simulation

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Fix a stock of variables $X = \{x_1, \dots, x_n\}$. Then we have

Linear Terms

$$\text{LTerm}(X) \ni r \mid r \cdot x \mid t + s$$


real number

Atomic Programs

$$\text{At}(X) \ni x := t \mid x'_1 = t_1, \dots, x'_n = t_n \text{ for } t$$


"run" the system of differential equations for t seconds

Hybrid Programs

$$\text{Prog}(X) \ni a \mid p ; q \mid \text{if } b \text{ then } p \text{ else } q \mid \text{while } b \text{ do } \{ p \}$$

How to interpret a hybrid program p ?

$$\llbracket \mathbf{x}' = 1 \text{ for } 1 \rrbracket : \mathbb{R} \longrightarrow (\text{trajectories over } \mathbb{R})$$

How to interpret a hybrid program p ?

$$\llbracket \mathbf{x}' = 1 \text{ for } 1 \rrbracket : \mathbb{R} \longrightarrow (\text{trajectories over } \mathbb{R})$$



i.e. functions from a time-domain into \mathbb{R}

Signature of the denotation suggests the use of (Elgot) monads

A monad T on Set is called Elgot if it has an **iteration** operator

$$\frac{f : X \rightarrow T(Y + X)}{f^\dagger : X \rightarrow TY}$$

that satisfies a certain set of laws

Intuitively, f^\dagger iterates over f until obtaining an output of type Y

Semantics without Iteration

Let $\sum_{d \in [0, \infty)} (\mathbb{R}^n)^{[0, d)}$ be the set of trajectories

It induces a monad on Set

$$\begin{aligned} X &\mapsto \mu\gamma. \left(\sum_{d \in [0, \infty)} (\mathbb{R}^n)^{[0, d)} \times \gamma + X \right) \\ &\cong \left(\sum_{d \in [0, \infty)} (\mathbb{R}^n)^{[0, d)} \right)^* \times X \end{aligned}$$

The fixpoint expression says a program either produces a trajectory and resumes or terminates with a value of type X

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The fixpoint expression says a program either produces a trajectory and resumes or terminates with a value of type X

Kleisli composition amounts to **concatenation** of lists of trajectories

Semantics without Iteration

Denotations $\llbracket p \rrbracket$ become functions of the type

$$\llbracket p \rrbracket : \mathbb{R}^n \longrightarrow \left(\sum_{d \in [0, \infty)} (\mathbb{R}^n)^{[0, d)} \right)^* \times \mathbb{R}^n$$

Example (with $n = 1$)

$$\llbracket x' = 1 \text{ for } 1 \rrbracket(0) = \left(\underbrace{[\lambda t \in [0, 1). 0 + t]}_{\text{list of size 1}}, 1 \right)$$

$$\begin{aligned} & \llbracket x' = 1 \text{ for } 1 ; x' = 1 \text{ for } 1 \rrbracket(0) \\ &= \left(\underbrace{[\lambda t \in [0, 1). 0 + t, \lambda t \in [0, 1). 1 + t]}_{\text{list of size 2}}, 2 \right) \end{aligned}$$

Semantics without Iteration

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$\llbracket \text{while true do } \{x' = 1 \text{ for } 1\} \rrbracket = ?$

Semantics with Iteration

Instead of using the **least** fixpoint we use the **greatest**

$$\begin{aligned} X &\mapsto \nu\gamma. \left(\sum_{d \in [0, \infty)} (\mathbb{R}^n)^{[0, d)} \times \gamma + X \right) \\ &\cong \left(\sum_{d \in [0, \infty)} (\mathbb{R}^n)^{[0, d)} \right)^* \times X + \left(\left(\sum_{d \in [0, \infty)} (\mathbb{R}^n)^{[0, d)} \right)^\omega \right) \end{aligned}$$

This is an instance of a universal construction which tells that

- the functor above is also a monad (henceforth denoted by \hat{H})
- the monad supports a partial **iteration** operator

$$\frac{f : X \rightarrow \hat{H}(Y + X)}{f^\dagger : X \rightarrow \hat{H}Y}$$

$$\frac{f : X \rightarrow \hat{H}(Y + X)}{f^\dagger : X \rightarrow \hat{H}Y}$$

f^\dagger iterates over f until the latter outputs a value of type Y ; and concatenates all lists of trajectories produced along the way

Example (with $n = 1$)

$$\begin{aligned} & \llbracket \text{while true do } \{x' = 1 \text{ for } 1\} \rrbracket(0) \\ &= \underbrace{[\lambda t \in [0, 1). 0 + t, \lambda t \in [0, 1). 1 + t, \lambda t \in [0, 1). 2 + t, \dots]}_{\text{infinite list of trajectories}} \end{aligned}$$

The proposed semantics is intensional e.g.

$$(x' = 1 \text{ for } 1) ; (x' = 1 \text{ for } 1) \neq (x' = 1 \text{ for } 2)$$

We wish to abstract away from invisible intermediate steps

This amounts to 'coherently' turning a sequence of trajectories into a single trajectory

From a Sequence of Trajectories into a Single Trajectory

Concatenation of Trajectories

$$\begin{aligned} & (\lambda t \in [0, d_1]. f_1(t)) \text{ ++ } (\lambda t \in [0, d_2]. f_2(t)) \\ & = \lambda t \in [0, d_1 + d_2]. \text{ if } t < d_1 \text{ then } f_1(t) \text{ else } f_2(t - d_1) \end{aligned}$$

Infinite Concatenation of Trajectories

$$f_1 \text{ ++ } f_2 \text{ ++ } \dots = \lambda t \in [0, \sum_{i \in \mathbb{N}} d_i]. (f_1 \text{ ++ } \dots \text{ ++ } f_j)(t) \text{ where } j \geq 1 \text{ is the smallest integer s.t. } t < \sum_{i \leq j} d_i$$

A Retraction Emerges

The previous operation induces a retraction

$$\hat{H} \begin{array}{c} \xrightarrow{\rho} \\ \xleftarrow{\nu} \end{array} \left(X \mapsto \sum_{d \in [0, \infty)} (\mathbb{R}^n)^{[0, d)} \times X + \sum_{d \in [0, \infty]} (\mathbb{R}^n)^{[0, d)} \right)$$

ρ resorts to concatenation of trajectories and ν is defined as

$$\text{inl}(f, x) \mapsto \text{inl}([f], x)$$

$$\text{inr}(f) \mapsto \text{inr}[f_{[0,1)}, f_{[1,2)}, \dots] \text{ if duration of } f \text{ equals } \infty$$

$$\text{inr}(f) \mapsto \text{inr}[f, !, !, \dots] \text{ otherwise}$$

Denote the functor on the right-hand side by H

An Extensional Hybrid Monad

$$\hat{H} \begin{array}{c} \xrightarrow{\rho \text{ (to extensional)}} \\ \xleftarrow{\nu} \end{array} H$$

H inherits from the monad \hat{H} (through ν and ρ)

- Kleisli composition
- an iteration operator

$$\frac{f : X \rightarrow H(Y + X)}{f^\dagger : X \rightarrow HY}$$

Interpretation via \mathbb{H} validates the aforementioned equality

$$(x' = 1 \text{ for } 1) ; (x' = 1 \text{ for } 1) = (x' = 1 \text{ for } 2)$$

and other expected ones, e.g.

$$\text{while true do } \{x' = 1 \text{ for } 1\} = \text{while true do } \{x' = 1 \text{ for } 2\}$$

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Also it gives rise to different kinds of while-loop ...

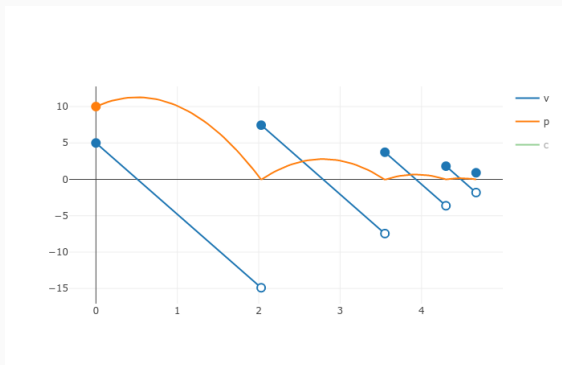
A Taxonomy of While Loops

	Non-progressive	Progressive	Zeno
Divergent	<pre>while (true) { x := x + 1 } }</pre>	<pre>while (true) { x := x + 1 ; (wait ϵ) } }</pre>	<pre>$\epsilon := 1$ while (true) { x := x + 1 ; (wait ϵ) $\epsilon := \frac{\epsilon}{2}$ } }</pre>
Convergent	<pre>x := 0 while (x \leq 10) { x := x + 1 } }</pre>	<pre>x := 0 while (x \leq 10) { x := x + 1 ; (wait ϵ) } }</pre>	N.A.

The tool Lince

An implementation of the semantics available at

<http://arcatools.org/assets/lince.html#fulllince>



More details in [Goncharov et al., 2020]

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Hybrid Components

We wish to combine the notion of **internal state** with that of **hybrid behaviour**

Useful for studying (the orchestration of) computational units that interact with physical processes

```
while true do { if f(readSens1(), readSens2())  
                then heatReactor()  
                else coolReactor() }
```

The State Monad

Let S be a set of states

Functorial part defined by $X \mapsto (S \times X)^S$

Kleisli composition amounts to carrying the current state from one computation to another

Does not support iteration

State Monad + Extensional Hybrid Monad

General categorical results allow us to combine both monads

The functorial part of the combined monad is given by

$$X \mapsto (\mathbb{H}(S \times X))^S$$

Kleisli composition is a combination of the previous compositions

State Monad + Extensional Hybrid Monad

General categorical results allow us to combine both monads

The functorial part of the combined monad is given by

$$X \mapsto (\mathbb{H}(S \times X))^S$$

Kleisli composition is a combination of the previous compositions

A hybrid component $c : \mathbb{A} \rightarrow \mathbb{B}$ is interpreted as a map

$$\llbracket c \rrbracket : \llbracket \mathbb{A} \rrbracket \rightarrow (\mathbb{H}(S \times \llbracket \mathbb{B} \rrbracket))^S$$

The combined monad inherits iteration from the hybrid one

$$\begin{aligned}f &: X \rightarrow (\mathbb{H}(S \times (Y + X)))^S \\ \Rightarrow f &: X \times S \rightarrow \mathbb{H}(S \times (Y + X)) \\ \Rightarrow f &: X \times S \rightarrow \mathbb{H}(S \times Y + S \times X) \\ \Rightarrow f^\dagger &: X \times S \rightarrow \mathbb{H}(S \times Y) \\ \Rightarrow f^\dagger &: X \rightarrow (\mathbb{H}(S \times Y))^S\end{aligned}$$

Theorem

The combined monad is Elgot

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We saw how to interpret hybrid behaviour in different settings

- hybrid automata
- hybrid while-language
- while-language + hybrid components

Currently working on the extension of the previous results to a quantitative setting

- quantitative bisimulation
- probabilities
- stability

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