

# Coalgebraic models for spatial logic based on transition systems with spatial structure

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- To study **abstract models** of spatial logic.
- To study **spatial** and **behavioural** features of systems in a unified (coalgebraic) framework.

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# What is spatial logic ?

In distributed computing verification must handle **behavioural** and **non-behavioural** properties:

- Location-dependent access rights to resources.
- Invariants of the communication topology and routing.
- Dynamically created objects and references.
- Security and secrecy features.

Spatial logic addresses both kinds of properties extending **temporal logic** with constructs for **spatial reasoning**.

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# Why abstract models ?

- To provide **language independent** models of spatial logic.
- To bring the study of models of spatial logic more in line with the models of temporal logic.
- To isolate spatial logic constructions, postulate their properties and analyze the corresponding **classes of models**.

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- Uniform treatment of time and space.
- Natural refinement of behavioural bisimulation.
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# An example: Topological properties of networks

A simple **spatial logic** for networks:

$x, y, z \in \text{Var}$

$A, B ::= l(x, y)$  % a link from  $x$  to  $y$

$x = y$  % equality

$\top$  % truth

$\neg A$  % negation

$A \wedge B$  % conjunction

$\exists x.A$  % existential quantification

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# Example (cont.)

## Models

- **Set of nodes**  $Nodes$
- **Nets**  $\mathcal{P}_\omega(Nodes \times Nodes)$
- **Spatial function**  $sp : Nets \rightarrow \mathcal{P}_\omega(Nets \times Nets)$

$$sp(N) = \begin{cases} \emptyset & \text{if } N = \emptyset, \\ \{(M, K) : N = M \cup K, M \cap K = \emptyset\} & \text{if } N \neq \emptyset. \end{cases}$$

# Example (cont.)

Satisfaction (classical connectives)

$\rho \in Env = Var \rightarrow Nodes$

$\models \subseteq Nets \times Env \times L$

- $N, \rho \models I(x, y)$  iff  $N = \{(\rho x, \rho y)\}$ .
- $N, \rho \models x = y$  iff  $\rho x = \rho y$ .
- $N, \rho \models \top$  always.
- $N, \rho \models \neg A$  iff  $N, \rho \not\models A$ .
- $N, \rho \models A \wedge B$  iff  $N, \rho \models A$  and  $N, \rho \models B$ .
- $N, \rho \models \exists x.A$  iff  $N, \rho[v/x] \models A$  for some  $v \in Nodes$ .

# Example (cont.)

## Satisfaction (spatial connectives)

- $N, \rho \models 0$  iff  $sp(N) = \emptyset$  (iff  $N = \emptyset$ ).
- $N, \rho \models A|B$  iff exists  $(M, K) \in sp(N)$  st  $M, \rho \models A$  and  $K, \rho \models B$ .

# Example (cont.)

## Some properties

- **No link to  $x$ :**

$$in_0(x) \triangleq \neg(\exists y.I(y, x)|\top)$$

- **$n + 1$  links to  $x$ :**

$$in_{n+1}(x) \triangleq \exists y.I(y, x)|in_n(x)$$

- **$n$  links from  $x$ :**

$out_n(x)$  defined similarly

- **Minimal net satisfying  $A$ :**

$$min(A) \triangleq A \wedge \neg(A|\neg 0)$$

- **$x$  is a node in the net:**

$$in\_net(x) \triangleq \exists y.(I(x, y) \vee I(y, x)|\top)$$

# Example (cont.)

## Non-recursive definition of path

- **A net is a path:**

$$is\_path(x, y) \triangleq$$

$$min[x = y \vee (in_0(x) \wedge out_1(x) \wedge in_1(y) \wedge out_0(y) \wedge$$

$$\forall z. z \neq x \wedge z \neq y \wedge in\_net(z) \Rightarrow in_1(z) \wedge out_1(z))]$$

- **Existence of a path:**

$$exists\_path(x, y) \triangleq is\_path(x, y) \uparrow \top$$

# Transition systems $\langle S, \rightarrow \rangle$ coalgebraically

The transitions from a state are **observed** through an observation function:

$$tr : S \rightarrow \mathcal{P}_\omega(S)$$

$$tr(s) = \{t : s \rightarrow t\}$$

$$s \rightarrow t \quad \text{iff} \quad t \in tr(s)$$



# States with internal structure

The internal structure of a state is **observed** through an appropriate function:

$$sp : S \rightarrow \text{Structures}(S)$$

$$sp(s) = ?$$

# A single coalgebra for space and time

The two observation functions may be combined into a single one:

$$\langle tr, sp \rangle : \mathcal{S} \rightarrow \mathcal{P}_\omega(\mathcal{S}) \times \text{Structures}(\mathcal{S})$$

$$\langle tr, sp \rangle(s) = \langle tr(s), sp(s) \rangle$$

# Two classes of spatial models of parallel composition

## Using pairs

$$sp : S \rightarrow \mathcal{P}_\omega(S \times S)$$

## Using (finite) multisets

$$sp : S \rightarrow \mathcal{M}(S)$$

# A simple spatial logic $L$

## HML-like with spatial operators

$$A, B ::= \top \mid \neg A \mid A \wedge B \mid \diamond A \mid 0 \mid A|B$$

## A simple spatial TS

$$tr : S \rightarrow \mathcal{P}_\omega(S)$$

$$sp : S \rightarrow \mathcal{P}_\omega(S \times S)$$

# Satisfaction $\models \subseteq S \times L$

- $s \models \top$  always.
- $s \models \neg A$  iff  $s \not\models A$ .
- $s \models A \wedge B$  iff  $s \models A$  and  $s \models B$ .
- $s \models \diamond A$  iff  $\exists t \in tr(s)$  such that  $t \models A$ .
- $s \models 0$  iff  $sp(s) = \emptyset$ .
- $s \models A|B$  iff  $\exists (t, u) \in sp(s)$  st  $t \models A$  and  $u \models B$ .

$sRt$  implies:

- 1  $sp(s) = \emptyset$  iff  $sp(t) = \emptyset$ , and
- 2  $\forall (s', s'') \in sp(s), \exists (t', t'') \in sp(t)$  such that  $s'Rt'$  and  $s''Rt''$ , and conversely.

## Definition

**Spatial bisimilarity**  $\sim_{sp}$  is the greatest bisimulation.

# Characterization of $\sim_{sp}$ by the purely spatial logic $L_{sp}$

## Definition

$s =_{L_{sp}} t$  iff  $\{A : s \models A\} = \{B : t \models B\}$ .

## Theorem

$\sim_{sp}$  coincides with  $=_{L_{sp}}$ .

The proof technique is similar to the one in the purely temporal case, where the logic is basically HML.

**Does a similar result hold for the combined space/time logic and system ?**

Yes, combining the proofs for the temporal and spatial cases.

# Classes of models described by axioms

- $A|0 \Leftrightarrow A$  (empty states are neutral with respect to parallel composition).
- $A|B \Rightarrow B|A$  (parallel composition is commutative).
- $(A|B)|C \Leftrightarrow A|(B|C)$  (parallel composition is associative).
- $0 \Rightarrow \neg \diamond T$  (empty states are inactive).
- $(\diamond A)|B \Rightarrow \diamond(A|B)$  (local transitions cause global transitions).



# Models of $A|B \Rightarrow B|A$

## Notation

$s \simeq t|u$  means  $(t, u) \in sp(s)$ .

## Property

The following statements are equivalent:

- 1  $s \models (A|B) \Rightarrow (B|A)$  for all formulas  $A$  and  $B$ .
- 2  $s \simeq t|u$  implies  $s \simeq u'|t'$  for some  $t' \sim t$  and  $u' \sim u$ .

# Spatial logic as a coalgebraic logic

Predicate lifting (Pattinson)

$$tr : S \rightarrow TS, \quad TS = \mathcal{P}_\omega(S)$$

$$s \models \diamond A \text{ iff } \exists t \in tr(s) \text{ such that } t \models A$$

$$\begin{aligned} s \in \llbracket \diamond A \rrbracket &\Leftrightarrow tr(s) \cap \llbracket A \rrbracket \neq \emptyset \\ &\Leftrightarrow tr(s) \in \{X : X \cap \llbracket A \rrbracket \neq \emptyset\} \end{aligned}$$

$$\llbracket \diamond A \rrbracket = tr^{-1}(\{X : X \cap \llbracket A \rrbracket \neq \emptyset\})$$

$$\lambda_S^\diamond : \mathcal{P}(S) \rightarrow \mathcal{P}(TS) \quad \lambda_S^\diamond(Y) = \{X : X \cap Y \neq \emptyset\}$$

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# Predicate lifting defined

## The spatial modalities

$$\lambda : \mathcal{P}^*(-)^n \rightarrow \mathcal{P}^* \circ T$$

$$\text{Void } \lambda_S^0 : 1 \rightarrow \mathcal{P}^*(TS) \quad TS = \mathcal{P}_\omega(S \times S)$$

$$\lambda_S^0(*) = \emptyset \quad \llbracket 0 \rrbracket = sp^{-1}(\lambda_S^0(*))$$

$$\text{Composition } \lambda_S^1 : \mathcal{P}^*(-)^2 \rightarrow \mathcal{P}^*(TS) \quad TS = \mathcal{P}_\omega(S \times S)$$

$$\lambda_S^1(X, Y) = \{Z : Z \cap (X \times Y) \neq \emptyset\}$$

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Another type of system:

$$tr : \mathcal{S} \rightarrow \mathcal{P}_\omega(\mathcal{S})$$

$$sp : \mathcal{S} \rightarrow \mathcal{M}(\mathcal{S})$$

Intuition:

$s \in \mathcal{S}$  is the parallel composition of the elements in  $sp(s)$ .

- 1 For any such system a Petri net can be constructed and vice-versa.
- 2 The constructions are functorial and form an adjunction.

**Main goal:** To describe causality and independence relations between events.

- **State  $s$  is local**  $sp(s) = [s]$
- **Set of local states**  $Loc(S) = \{s \in S : s \text{ is local}\}$
- **Transition  $s \rightarrow t$  is local**  
If  $p \rightarrow q$  with  $sp(s) = sp(p) \oplus M$  and  $sp(t) = sp(q) \oplus M$ , then  $M = []$ .
- **Extension of  $\rightarrow$  to  $\mathcal{M}(Loc(S))$**   
 $P \rightarrow Q$  iff exists  $s \rightarrow t$  and  $M$  st  $P = sp(s) \oplus M$  and  $Q = sp(t) \oplus M$

# Axioms of spatial TS's

- 1  $sp(s) \in \mathcal{M}(Loc(S))$ .
- 2  $P \subseteq sp(s)$  implies  $P = sp(t)$  for some  $t$ .
- 3  $sp(s) \rightarrow P$  implies  $s \rightarrow t$  for some  $t$  st  $sp(t) = P$ .

# Morphism $f : S \rightarrow S'$ of spatial TS's

- 1  $sp' \circ f = \mathcal{M}(f) \circ sp.$
- 2  $tr' \circ f = \mathcal{P}_\omega(f) \circ tr.$
- 3  $s \rightarrow t$  local in  $S$  implies  $f(s) \rightarrow f(t)$  local in  $S'$ .
- 4  $\mathcal{P}_\omega(f) \circ St = St' \circ \mathcal{M}(f),$

where  $St : \mathcal{M}(Loc(S)) \rightarrow \mathcal{P}_\omega(S)$  is given by

$$St(M) = \{s \in S : sp(s) \subseteq M\}.$$

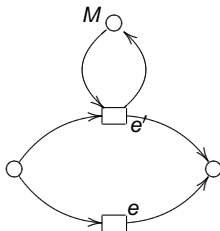


# Petri nets $N = (B, E, pre, post)$

$$pre, post : E \rightarrow \mathcal{M}(B)$$

**Axiom**  $pre(e') = pre(e) \oplus M$  and  $post(e') = post(e) \oplus M$  imply  $M = []$  and  $e = e'$ .

Kind of situation discarded by the axiom:



# Morphism $f : N \rightarrow N'$ of Petri nets

Pair of functions

$$f_B : B \rightarrow B', \quad f_E : E \rightarrow E'$$

such that

- 1  $pre' \circ f_E = \mathcal{M}(f_B) \circ pre.$
- 2  $post' \circ f_E = \mathcal{M}(f_B) \circ post.$
- 3  $En' \circ \mathcal{M}(f_B) = \mathcal{P}_\omega(f_E) \circ En.$

Here  $En : \mathcal{M}(B) \rightarrow \mathcal{P}_\omega(E)$  gives the set  $En(M)$  of events enabled by  $M \in \mathcal{M}(B)$ .

# From a Petri net $N$ to a spatial TS $ns(N)$

- 1  $ns(N) = \mathcal{M}(B)$ .
- 2  $sp(M) = [[b] : b \in M]$ .
- 3  $tr(M) = \{M' : M \xrightarrow{e} M'\}$  for some event  $e$ .

# From a spatial TS $S$ to a Petri net $sn(S)$

- 1  $B = Loc(S)$ .
- 2  $E = Loc(Tr)$ .
- 3  $pre(s \rightarrow t) = sp(s)$ .
- 4  $post(s \rightarrow t) = sp(t)$ .

# Relating the functors

The functor

$$sn : \text{Spatial TS's} \rightarrow \text{Petri nets}$$

is left adjoint to the functor

$$ns : \text{Petri nets} \rightarrow \text{Spatial TS's.}$$

# A spatial TS for CCS

The transition function is defined as usual.

The spatial function  $sp : Proc \rightarrow \mathcal{P}_\omega(Proc \times Proc)$  is defined by:

$$sp(P) = \begin{cases} \emptyset & \text{if } P \equiv 0, \\ \{(P_1, P_2) : P \equiv_{sp} P_1 | P_2\} & \text{otherwise.} \end{cases}$$

$\equiv_{sp}$  is defined as  $\equiv$  except for the conditions

$$P|0 \equiv 0 \quad \text{and} \quad \nu x.0 \equiv 0$$

to guarantee that  $sp(P)$  is a finite set.

- Systematic study of classes of models.
- Spatial operators related to the use of names.
- Predicate liftings for the adjoint modalities.
- Other non-interleaving models of concurrency.