

Quality of Service Through Connector Composition



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Work in Progress



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Motivation



- Providers use components and services from multiple vendors to compose new offerings.
- How to model, analyze, and ensure end-to-end QoS in large-scale distributed systems?
 - Requirements:
 - Wide range of quality attributes
 - Expressiveness/coverage
 - Architectural fidelity
 - Compositional
 - Consistent treatment of all components, services, and connectors.

Quality of Service



□ Definition:

- QoS of a system is a measure of comparing the expected values with the experienced values of a set of attributes of that system.
 - Expected value?
 - Experienced value?

QoS for Behavioral Models

- Behavioral abstraction proposed in Reo offers a suitable model for composition of components/actors and connectors into a system.
 - Computational expressiveness
 - Architectural fidelity
 - Compositional
 - Consistent treatment of components, services, and connector.
- Can this model be extended to accommodate QoS concerns?
 - How?
 - Preserve compositionality?

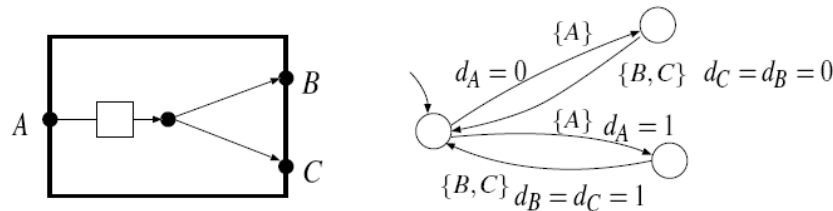
TDS Semantics



- The TDS semantics of Reo is too fine-grained.
 - Actual time-stamp values often do not matter.
 - Precise relations among specific time-stamp values in different streams:
 - Sometimes intended
 - Sometimes coincidental
 - Atomicity conveyed as equality of real numbers:
 - Too restrictive
 - Unrealistic, especially in distributed systems

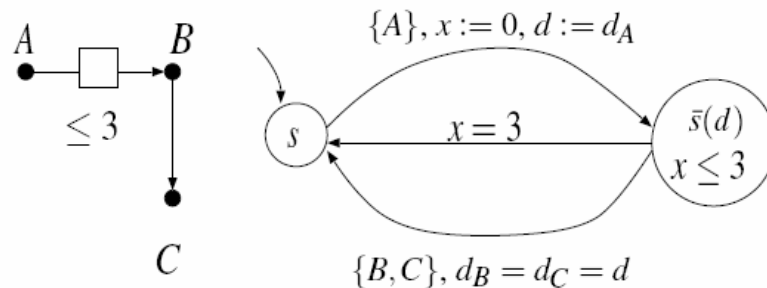
Constraint Automata Semantics

- Abstracts away the time-stamp values.
- Focuses directly on atomicity and order.



Timed Constraint Automata

- Extension of Constraint Automata with time, analogous to Timed Automata.
- States have local clocks that are reset by transitions.



Experience vs. Expectation

- Both TDS and CA models use *successful interaction* as the fundamental tick of progress.
- We need new vocabulary to talk about *attempt vs. completion* of an interaction.
- Completion can be due to
 - Success (i.e., "the tick" for TDS and CA)
 - Time-out

Intermittent Operation Stream

- An Intermittent Operations Stream (IOS) is a twin pair of streams represented as $[\kappa, k]$
- The operation stream $\kappa \in (Data \cup \{\uparrow\})^\omega$ $\kappa(0) \in Data$
- The interval stream $k \in \{v \mid (v = @r \vee v = r) \wedge r \in R_+\}^\omega$
- The clock offset of the interval stream k is $k_{-1} \in R_+$
- For convenience, we define $k(-1) = k_{-1}$

		0	1	2	3	4	5	6	...
κ		x_0	x_1	x_2	x_3	$x_4 = \top$	x_5	x_6	...
k	$k_{-1} = 0$	0.5	@0.6	0.4	0.3	0.5	1	@4	...

Plugging of an IOS onto a TDS

Definition 1 Let $\langle \alpha, a \rangle$ represents the TDS at a boundary node of a circuit. We denote by $[\kappa, k] \vdash \langle \alpha, a \rangle$ the plugging of the IOS $[\kappa, k]$ onto $\langle \alpha, a \rangle$, where:

1. $\langle \alpha, a \rangle = \mathcal{S}(\kappa, t)$, for some completion time stream $t \in \mathbb{R}_+^\omega$
2. For operation stream ψ and $p \in \mathbb{R}_+^\omega$, the function $\mathcal{S}(\psi, p)$ is defined as:

$$\mathcal{S}(\psi, p) \equiv \begin{cases} p(0) < p(1) ? \langle \psi(0).b, p(0).b \rangle : \langle \beta, b \rangle \wedge \langle \beta, b \rangle = \mathcal{S}(\psi'', p'') & \text{if } \psi(1) = \top \\ \langle \psi(0).b, p(0).b \rangle \wedge \langle \beta, b \rangle = \mathcal{S}(\psi', p') & \text{otherwise} \end{cases}$$

3. For $i \geq 0$ the request time stream $r \in \mathbb{R}_+^\omega$ is defined as

$$r(i) \equiv \begin{cases} v + k_{-1} & \text{if } k(i) = @v \\ k(i) + t(i-1) & \text{otherwise} \end{cases}$$

where $t(-1) = k_{-1}$

4. Streams r and t satisfy the infinite set of constraints $\{\mathcal{C}_0, \mathcal{C}_1, \mathcal{C}_2, \dots\}$, where for $i \geq 0$:

$$\mathcal{C}_i \equiv \begin{cases} t(i) = v + k_{-1} & \text{if } \kappa(i) = \top \wedge k(i) = @v \\ t(i) = r(i-1) + k(i) & \text{if } \kappa(i) = \top \wedge k(i) \neq @v \\ r(i) \leq t(i) < r(i+1) & \text{otherwise} \end{cases}$$

Example - 1/5

- Consider plugging $[\kappa, k] \vdash \langle \alpha, a \rangle$

		0	1	2	3	4	5	6	...
κ		x_0	x_1	x_2	x_3	$x_4 = \top$	x_5	x_6	...
k	$k_{-1} = 0$	0.5	@0.6	0.4	0.3	0.5	1	@4	...

- Derive requests time stream r (item 3):

		0	1	2	3	4	5	6	...
κ		x_0	x_1	x_2	x_3	$x_4 = \top$	x_5	x_6	...
k	$k_{-1} = 0$	0.5	@0.6	0.4	0.3	0.5	1	@4	...
r		$0.5 + k_{-1}$	$0.6 + k_{-1}$	$0.4 + t(1)$	$0.3 + t(2)$	$0.5 + t(3)$	$1 + t(4)$	$4 + k_{-1}$...

- Constraints C yield completion time stream t (item 4):

$$\begin{aligned}
 C_0 & 0.5 + k_{-1} \leq t(0) < 0.6 + k_{-1} \\
 C_1 & 0.6 + k_{-1} \leq t(1) < 0.4 + t(1) \\
 C_2 & 0.4 + t(1) \leq t(2) < 0.3 + t(2) \\
 C_3 & 0.3 + t(2) \leq t(3) < 0.5 + t(3) \\
 C_4 & & t(4) = 0.3 + t(2) + 0.5 \\
 C_5 & 1 + t(4) \leq t(5) < 4 + k_{-1} \\
 C_6 & 4 + k_{-1} \leq t(6) < \dots \\
 & \vdots & \vdots
 \end{aligned}$$

Example - 2/5

- We obtain $\langle \alpha, a \rangle = \mathcal{S}(\kappa, t)$ from the following table by dropping every column whose data value is “_”:

α	x_0	x_1	x_2	$\bar{a}(3) < \bar{a}(4)?x_3:-$	x_5	x_6	x_7	...
a	$\bar{a}(0)$	$\bar{a}(1)$	$\bar{a}(2)$	$\bar{a}(3)$	$\bar{a}(5)$	$\bar{a}(6)$	$\bar{a}(7)$...

- where

$$\begin{aligned}
 0.5 + k_{-1} &\leq \bar{a}(0) < 0.6 + k_{-1} \\
 0.6 + k_{-1} &\leq \bar{a}(1) < 0.4 + \bar{a}(1) \\
 0.4 + \bar{a}(1) &\leq \bar{a}(2) < 0.3 + \bar{a}(2) \\
 0.3 + \bar{a}(2) &\leq \bar{a}(3) < 0.5 + \bar{a}(3) \\
 &\bar{a}(4) = 0.3 + \bar{a}(2) + 0.5 \\
 1 + \bar{a}(4) &\leq \bar{a}(5) < 4 + k_{-1} \\
 4 + k_{-1} &\leq \bar{a}(6) < \dots \\
 &\vdots
 \end{aligned}$$

Example - 3/5

- Consider plugging $[\lambda, l] \vdash \langle \beta, b \rangle$

		0	1	2		3	4	5	6	...
λ		y_0	y_1	$y_2 = \top$		y_3	y_4	y_5	y_6	...
l	$L_{-1} = 0.8$	0.1	0.1	4		@5.3	0.7	1	@8	...

- Derive requests time stream r (item 3):

		0	1	2	3	4	5	6	...
λ		y_0	y_1	$y_2 = \top$	y_3	y_4	y_5	y_6	...
l	$L_{-1} = 0.8$	0.1	0.1	4	@5.3	0.7	1	@8	...
r		$0.1 + L_{-1}$	$0.1 + t(0)$	$4 + t(1)$	$5.3 + L_{-1}$	$0.7 + t(3)$	$1 + t(4)$	$8 + k_{-1}$...

- Constraints C yield interaction time stream t (item 4):

$$\begin{aligned}
 C_0 & 0.1 + L_{-1} \leq t(0) < 0.1 + t(0) \\
 C_1 & 0.1 + t(0) \leq t(1) < 4 + t(1) \\
 C_2 & t(2) = 0.1 + t(0) + 4 \\
 C_3 & 5.3 + L_{-1} \leq t(3) < 0.7 + t(3) \\
 C_4 & 0.7 + t(3) \leq t(4) < 1 + t(4) \\
 C_5 & 1 + t(4) \leq t(5) < 8 + L_{-1} \\
 C_6 & 8 + L_{-1} \leq t(6) < \dots
 \end{aligned}$$

Example - 4/5

- We obtain $\langle \beta, b \rangle = \mathcal{S}(\lambda, t)$ from the following table by dropping every column whose data value is “_”:

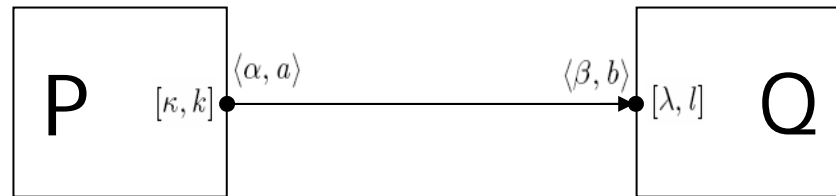
$$\begin{array}{cccccccc}
 \beta & y_0 & \bar{b}(1) & \bar{b}(2) & y_3 & y_4 & y_5 & y_6 & y_7 & \dots \\
 b & \bar{b}(0) & \bar{b}(1) & \bar{b}(2) & \bar{b}(3) & \bar{b}(4) & \bar{b}(5) & \bar{b}(6) & \bar{b}(7) & \dots
 \end{array}$$

- where

$$\begin{array}{l}
 0.1 + L_1 \leq \bar{b}(0) < 0.1 + \bar{b}(0) \\
 0.1 + \bar{b}(0) \leq \bar{b}(1) < 4 + \bar{b}(1) \\
 \bar{b}(2) = 0.1 + \bar{b}(0) + 4 \\
 5.3 + L_1 \leq \bar{b}(3) < 0.7 + \bar{b}(3) \\
 0.7 + \bar{b}(3) \leq \bar{b}(4) < 1 + \bar{b}(4) \\
 1 + \bar{b}(4) \leq \bar{b}(5) < 8 + L_1 \\
 8 + L_1 \leq \bar{b}(6) < \dots \\
 \vdots
 \end{array}$$

Example - 5/5

- If a producer P and a consumer Q are connected by a Sync channel, we have:



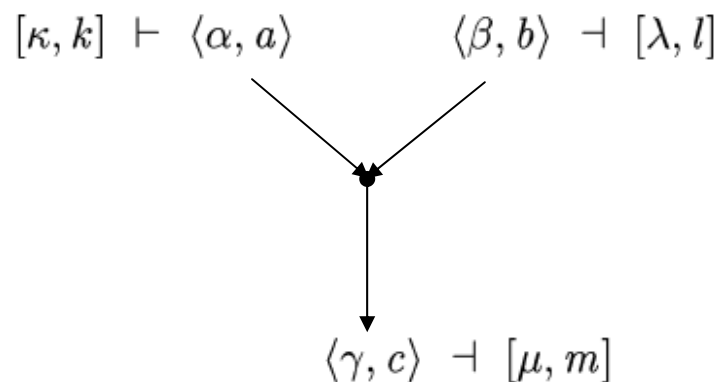
$$\begin{array}{ll}
 0.5 + k_{-1} \leq a(0) & \wedge \quad 0.1 + l_{-1} \leq b(0) \\
 0.6 + k_{-1} \leq a(1) & \wedge \quad 0.1 + b(0) \leq b(1) \leq 0.1 + b(0) + 4 \\
 0.4 + a(1) \leq a(2) & \wedge \quad 5.3 + l_{-1} \leq b(2) \\
 0.3 + a(2) \leq a(3) \leq 0.3 + a(2) + 0.5 & \wedge \quad 0.7 + b(3) \leq b(3) \\
 1 + a(3) \leq a(4) & \wedge \quad 1 + b(4) \leq b(4) \\
 4 + k_{-1} \leq a(5) & \wedge \quad 8 + l_{-1} \leq b(5) \\
 \vdots & \vdots
 \end{array}$$

- In theory, Sync channel means $a=b$. But in practice, we may want to impose:

$$\begin{array}{l}
 |a - b| \leq s \\
 a(i) \leq b(i) < a(i+1) \leq b(i+1) \\
 a(i+1) - a(i) \geq t
 \end{array}$$

Connector Imposed Delays

- The exclusion of $a(i)=b(j)$ by the merger affects the completion times of the operations as much as the IOSs do.



Performance

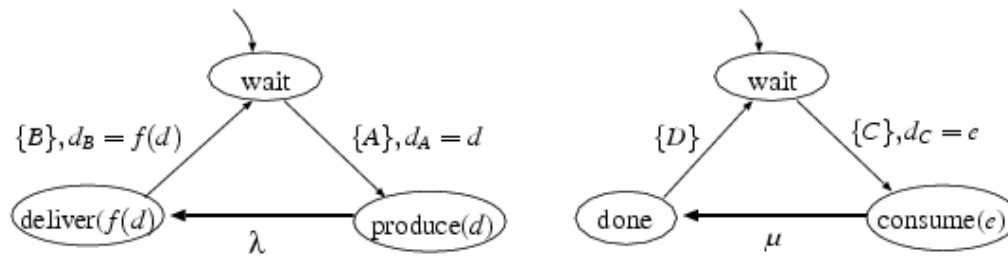
- Fixing specific values for k and l , we can quantify P 's experience in a specific run of the system:
 - Average delay between request and completion.
 - Frequency of timeouts versus successful completion.



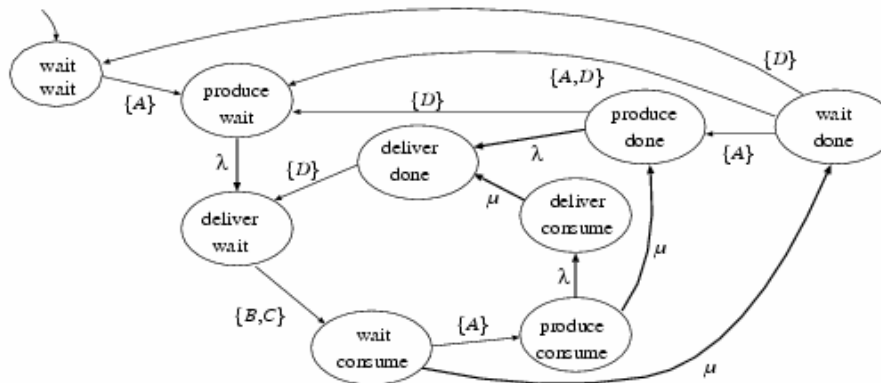
- To properly characterize system performance, we need stochastic variables instead of exact values.

Stochastic Constraint Automata

- Constraint Automata with stochastic (Markov chain) transitions as well as interactive transitions.

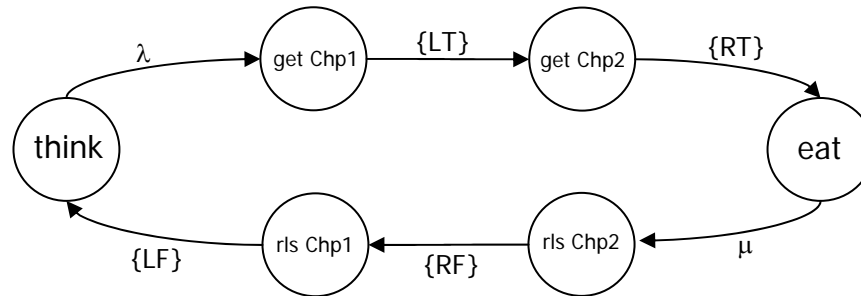


- CA product is extended to allow composition of SCA



SCA Model of a Dining Philosopher

- Stochastic Constraint Automaton for a dining philosopher.



Q-Algebra

- We define a general purpose framework for QoS measures: Q-Algebra.
- "Constraint Semirings" have been used to model QoS values in the past.
- Q-Algebras extend Constraint Semirings with a composition operator.
- We can add these costs to automata models or process calculi to make *compositional* models of *concurrent* systems.

Constraint Semirings

- Constraint semirings model QoS values with a domain and two operations:
 - + picks between values.
 - * combines them.

- both operations are associative and have identities, * is commutative, + distributes over *, etc.

- Examples:
 - Memory assigned:
Domain: $\mathbf{Z} \cup \{\infty\}$, Choose: min, Combine: +
 - Access control
 - Domain: $2^{\text{principals}}$, Choose: union, Combine: intersect

Composition Operators

- With concurrent processes there are two ways to combine values: sequentially $*$ and concurrently $|$
- We define a QoS Algebra: $(D, +, *, |, 0, 1)$ such that $(D, +, *, 0, 1)$ and $(D, +, |, 0, 1)$ are constraint semirings.
- % of CPU needed:
 - Domain: $\{1, \dots, 100\}$ Choose: max,
 - Combine concurrent: + Combine sequential: max
- Memory assignment:
 - Domain: $\mathbf{Z} \cup \{\infty\}$ Choose: max
 - Combine concurrent: + Combine sequential: +

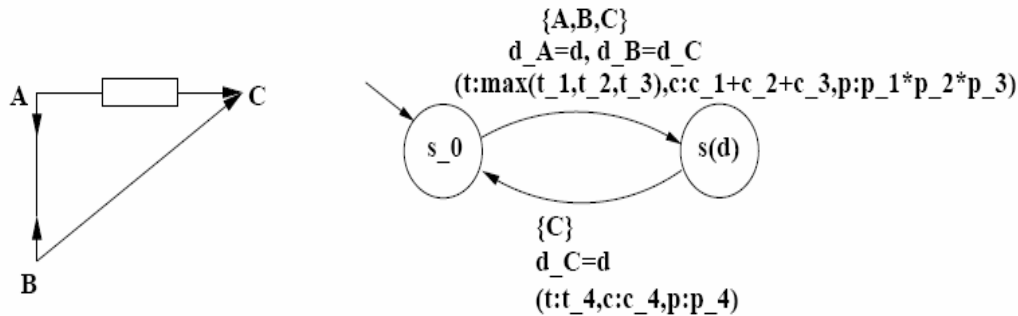
Overview of Q-Algebra

- ❑ Q-Algebra is a framework that can be used to model many kinds of QoS value.
- ❑ We distinguish between the concurrent and sequential combination of QoS values.
- ❑ Q-Algebra costs can be added to a range of formalisms.
- ❑ We have defined an automata model with these costs that can be model checked for cost based properties.

Quantified Constraint Automata

Definition 4. A *Q-Constraint Automata* is a tuple $\mathcal{Q} = (S, s_0, \mathcal{N}, R, \longrightarrow)$ where

- S is a set of states, also called configurations,
- $s_0 \in S$ is its initial state,
- \mathcal{N} is a finite set of nodes,
- $R = (C, \oplus, \otimes, \odot, \mathbf{0}, \mathbf{1})$ is a labeled *Q-algebra* with domain C of costs,
- $\longrightarrow \subseteq \bigcup_{N \subseteq \mathcal{N}} S \times \{N\} \times DC(N) \times C \times S$, called the transition relation.



Product of Q-Constraint Automata

- Analogous to product of Constraint Automata, but costs are (parallel-) composed on synchronizing transitions.

Definition 5. The product of two QCA $\mathcal{Q}_1 = (S_1, s_{0,1}, \mathcal{N}_1, R_1, \longrightarrow_1)$ and $\mathcal{Q}_2 = (S_2, s_{0,2}, \mathcal{N}_2, R_2, \longrightarrow_2)$ where R_1 and R_2 are consistent Q-algebra is defined as a Q-Constraint Automata $\mathcal{Q}_1 \boxtimes \mathcal{Q}_2$ with the components

$$(S_1 \times S_2, (s_{0,1}, s_{0,2}), \mathcal{N}_1 \times \mathcal{N}_2, R_1 \boxtimes R_2, \longrightarrow)$$

where \longrightarrow is given by the following rules:

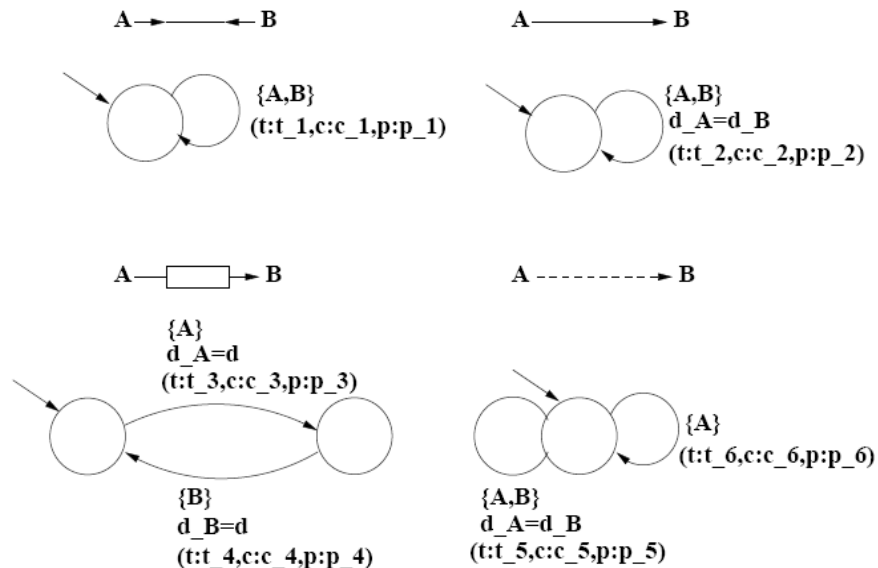
- If $s_1 \xrightarrow{N_1, g_1, c_1}_1 s'_1$, $s_2 \xrightarrow{N_2, g_2, c_2}_2 s'_2$, $N_1 \cap \mathcal{N}_2 = N_2 \cap \mathcal{N}_1$ and $g_1 \wedge g_2$ is satisfiable, then $\langle s_1, s_2 \rangle \xrightarrow{N_1 \cup N_2, g_1 \wedge g_2, c_1 \odot c_2} \langle s'_1, s'_2 \rangle$.
- If $s_1 \xrightarrow{N, g, c}_1 s'_1$, where $N \cap \mathcal{N}_2 = \emptyset$ then $\langle s_1, s_2 \rangle \xrightarrow{N, g, c} \langle s'_1, s_2 \rangle$.
- If $s_2 \xrightarrow{N, g, c}_2 s'_2$, where $N \cap \mathcal{N}_1 = \emptyset$ then $\langle s_1, s_2 \rangle \xrightarrow{N, g, c} \langle s_1, s'_2 \rangle$.

Example - 1/3

□ QoS for basic Reo channels:

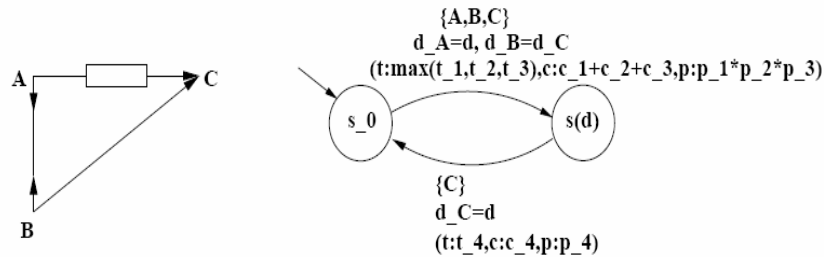
- shortest time: $(\mathbb{R}_+ \cup \{\infty\}, \min, +, \max, \infty, 0)$
- cost: $(\mathbb{R}_+ \cup \{\infty\}, \min, +, +, \infty, 0)$
- reliability: $([0, 1], \max, \times, \times, 0, 1)$

□ QCA for 4 basic Reo channels:



Example - 2/3

□ Consider the alternator circuit and its QCA



□ The total cost of the connector is:

$$t = \max(t_1, t_2, t_3) + t_4$$

$$c = \sum_{i=1}^4 c_i$$

$$p = \prod_{i=1}^4 p_i$$

Example - 3/3

- Two available providers:

	provider1	provider2
SyncDrain	(t ₁ =0,c ₁ =3,p ₁ =1)	(t ₁ =0.1,c ₁ =2,p ₁ =1)
Sync	(t ₂ =1,c ₂ =2,p ₂ =0.95)	(t ₂ =1,c ₂ =8,p ₂ =0.99)
FIFO1	(t ₃ =1,c ₃ =2,p ₃ =0.9, t ₄ =0.5,c ₄ =2,p ₄ =0.9)	(t ₃ =1,c ₃ =5,p ₃ =1, t ₄ =1,c ₄ =5,p ₄ =0.99)
LossySync	(t ₅ =1,c ₅ =2,p ₅ =0.95, t ₆ =0.1,c ₆ =1,p ₆ =0.95)	(t ₅ =1,c ₅ =3,p ₅ =0.99, t ₆ =0.2,c ₆ =0.5,p ₆ =0.99)

- Requirements:

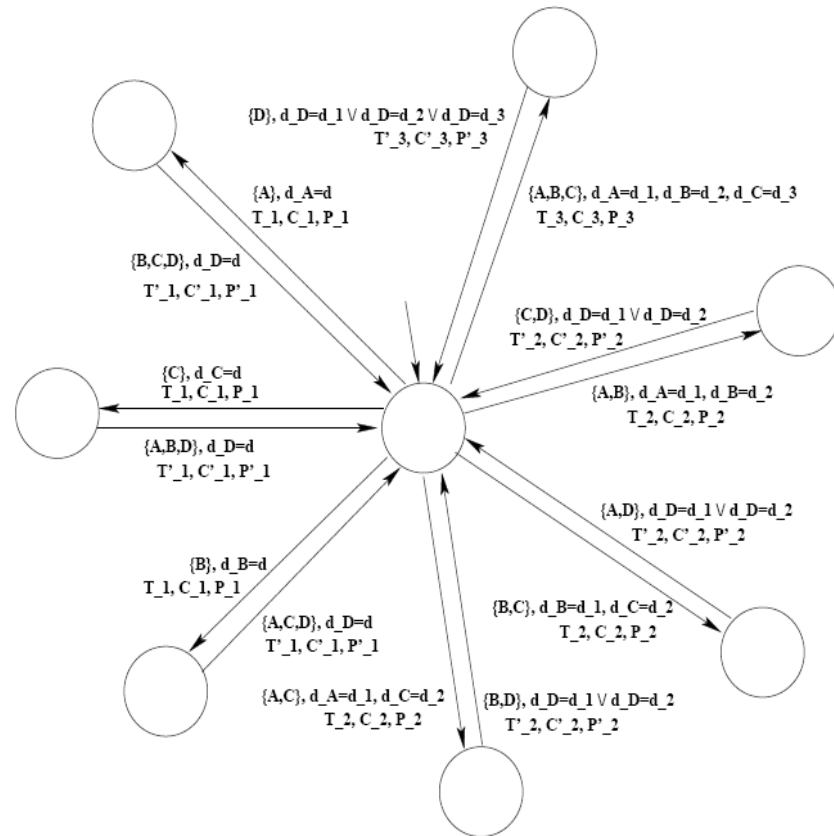
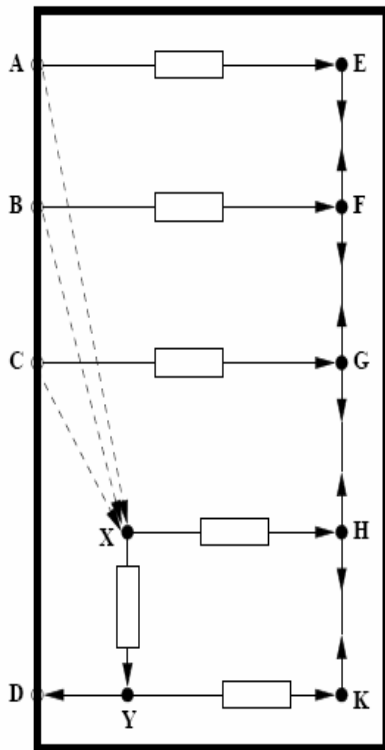
- Cost no more than 15
- Reliability greater than 90%

- Alternatives:

- All provider 1: t=1.5, c=9, p=0.7696
- All provider 2: t=2, c=20, p=0.9801
- Sync by provider 1; SyncDrain and FIFO1 by provider 2: t=2, c=14, p=0.9405

Example: Discriminator Circuit

Composed QCA after hiding



Example: Alternative Deployments

□ Composed cost values:

$$T_1 = \max\{t_3, t_5\}$$

$$C_1 = 3 \times c_3 + c_5$$

$$P_1 = p_3^3 \times p_5$$

$$T'_1 = \max\{t_2, t_3, t_3 + t_4, t_6\} + \max\{t_4, t_1 + t_4\}$$

$$C'_1 = 4 \times c_1 + c_2 + 3 \times c_3 + 6 \times c_4 + 2 \times c_6$$

$$P'_1 = p_1^4 \times p_2 \times p_3^3 \times p_4^6 \times p_6^2$$

$$T_2 = \max\{t_3, t_5\}$$

$$C_2 = 4 \times c_3 + 2 \times c_5$$

$$P_2 = p_3^4 \times p_5^2$$

$$T'_2 = \max\{t_2, t_3, t_3 + t_4, t_6\} + \max\{t_4, t_1 + t_4\}$$

$$C'_2 = 4 \times c_1 + c_2 + 2 \times c_3 + 7 \times c_4 + c_6$$

$$P'_2 = p_1^4 \times p_2 \times p_3^2 \times p_4^7 \times p_6$$

$$T_3 = \max\{t_3, t_5\}$$

$$C_3 = 5 \times c_3 + 3 \times c_5$$

$$P_3 = p_3^5 \times p_5^3$$

$$T'_3 = \max\{t_2, t_3 + t_4\} + \max\{t_4, t_1 + t_4\}$$

$$C'_3 = 4 \times c_1 + c_2 + c_3 + 7 \times c_4$$

$$P'_3 = p_1^4 \times p_2 \times p_3 \times p_4^7$$

□ All provider 1:

$$T_1 = T_2 = T_3 = 1, T'_1 = T'_2 = T'_3 = 2,$$

$$C_1 = 8, C_2 = 12, C_3 = 16, C'_1 = 34, C'_2 = 33, C'_3 = 30,$$

$$P_1 \approx 0.69, P_2 \approx 0.48, P_3 \approx 0.5, P'_1 \approx 0.33, P'_2 \approx 0.39, P'_3 \approx 0.41$$

□ All provider 2:

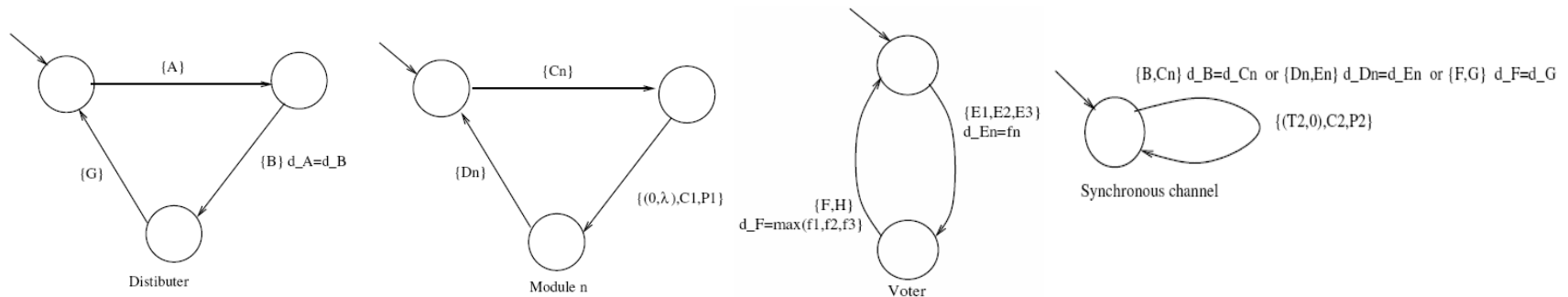
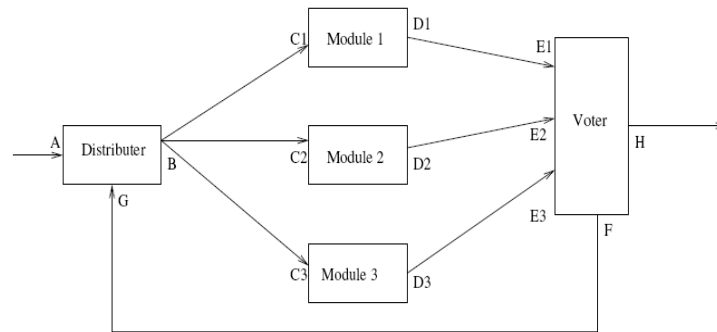
$$T_1 = T_2 = T_3 = 1, T'_1 = T'_2 = T'_3 = 3.1,$$

$$C_1 = 18, C_2 = 26, C_3 = 34, C'_1 = 62, C'_2 = 61.5, C'_3 = 56,$$

$$P_1 = 0.99, P_2 \approx 0.98, P_3 \approx 0.97, P'_1 \approx 0.89, P'_2 \approx 0.89, P'_3 \approx 0.92$$

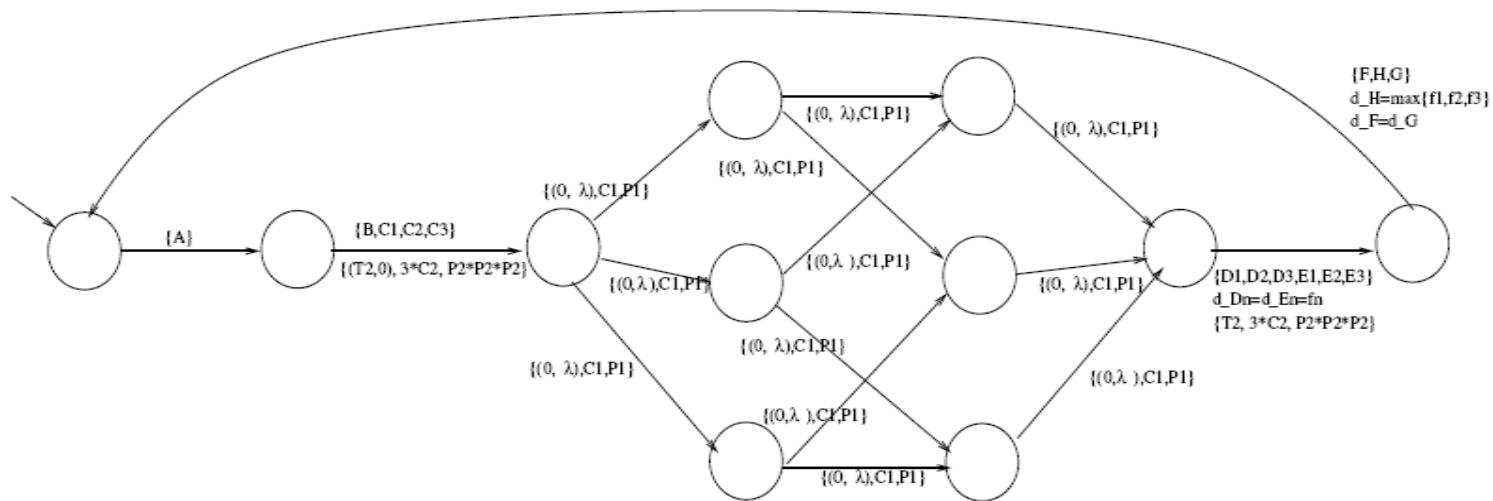
Stochastic Q-Constraint Automata

Example: Triple modular redundancy system



Composed SQCA for TMR System

- How to hide internal states involving stochastic transition?



Summary



- ❑ Reo offers a powerful structural framework for composition of QoS properties.
- ❑ QCA (stochastic or otherwise) serve as good models for both Reo circuits and components/subsystems with QoS properties.
- ❑ Choices of actual composition operators for Q-algebras in some domains is non-trivial.
- ❑ Hiding of intermediate states/transitions of composed SQCA?