## Quantum Search

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HASLab
HIGH-ASSURANCE
SOFTWARE LABORATORY

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## Putting inversion into practice

## Analysis of Grover's performance

## Multiple Solutions

## Grover's Problem

## The Problem

Take a function $f:\{0,1\}^{n} \rightarrow\{0,1\}$
There exists one $x \in\{0,1\}^{n}$ such that $f(x)=1$
Discover the $x$
Classically, need to evaluate $f 2^{n}$ times in the worst case

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Quantumly, need to evaluate $f$ around $\sqrt{2^{n}}$ times

## Applications

Grover's problem occurs in a multitude of scenarios

- Searching through unstructured databases
- Finding passwords
- Route planning
- Solving SAT problems
- NP-problems in general


## Key Ideas

Like in all previous quantum algorithms, we will rely on

1. superposition
2. interference (to decrease amplitude of wrong answers and increase amplitude of the right ones)

## Key Ideas: Superposition

Take $f:\{0,1\}^{2} \rightarrow\{0,1\}$ with $f(10)=1$


## Key Ideas: Interference pt. I

Inversion about the mean: $(x \mapsto(-x+$ mean $)+$ mean $)$


Intuitively mass of some states was given to others

## Key Ideas: Interference pt. II

Mind the following particular case of inversion about the mean


Intuitively, mass of wrong answers was given to the right one

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## The Steps

1. Put all possible answers in uniform superposition
2. Negate phases of the right answer
3. Invert about the mean
4. Repeat steps 2 and 3 until ensured we will measure the right answer with high probability $\left(\approx \sqrt{2^{n}}\right.$ times $)$

## The Circuit


N.B. It is often convenient to omit the bottom qubit

## Adding Local Phases

Recall from last lectures the notion of phase kickback and that

$$
U_{f}|x\rangle|-\rangle=(-1)^{f(x)}|x\rangle|-\rangle
$$

In particular, if $x$ is as solution of $f$ we obtain a phase flip

$$
U_{f}|x\rangle|-\rangle=(-1)|x\rangle|-\rangle
$$

## Inversion About the Mean pt. I

We start with the operation that phase flips basis states different from $|0\rangle$, i.e.

$$
P=2|0\rangle\langle 0|-I
$$

Then we calculate

$$
\begin{aligned}
& H^{\otimes n}(2|0\rangle\langle 0|-I) H^{\otimes n} \\
& =\left(H^{\otimes n}(2|0\rangle\langle 0|)-H^{\otimes n}\right) H^{\otimes n} \\
& =H^{\otimes n}(2|0\rangle\langle 0|) H^{\otimes n}-H^{\otimes n} H^{\otimes n} \\
& =2 H^{\otimes n}|0\rangle\langle 0| H^{\otimes n}-I
\end{aligned}
$$

Denoting $H^{\otimes n}|0\rangle$ by $|\psi\rangle$ we obtain,

$$
2|\psi\rangle\langle\psi|-1
$$

## Inversion About the Mean pt. II

1. Prove that $|\psi\rangle\langle\psi|=\frac{1}{N} \sum_{x, y \in N}|x\rangle\langle y|$ with $N=2^{n}$
2. Prove that $2|\psi\rangle\langle\psi|-I$ is the desired inversion about the mean

## Inversion About the Mean pt. III

$$
\begin{aligned}
& \left(2 \frac{1}{N} \sum_{x, y \in N}|x\rangle\langle y|-I\right) \sum_{k \in N} \alpha_{k}|k\rangle \\
& =2 \frac{1}{N} \sum_{x, y \in N}|x\rangle\langle y|\left(\sum_{k \in N} \alpha_{k}|k\rangle\right)-\sum_{k} \alpha_{k}|k\rangle \\
& =2 \frac{1}{N} \sum_{x, y \in N}\left(\sum_{k \in N} \alpha_{k}\langle y, k\rangle|x\rangle\right)-\sum_{k} \alpha_{k}|k\rangle \\
& =2 \frac{1}{N} \sum_{x, y \in N} \alpha_{y}|x\rangle-\sum_{k} \alpha_{k}|k\rangle \\
& =2 \underbrace{\frac{1}{N} \sum_{y \in N} \alpha_{y}}_{\text {mean }} \sum_{x \in N}|x\rangle-\sum_{k} \alpha_{k}|k\rangle \\
& =\sum_{x \in N} 2 \alpha|x\rangle-\sum_{k} \alpha_{k}|k\rangle \\
& =\sum_{k \in N}\left(-\alpha_{k}+2 \alpha\right)|k\rangle
\end{aligned}
$$

## Example: $N=2^{3}=8, w=011$



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At the end probability of measuring 011 is $\approx 94.5 \%$

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Let $|w\rangle$ be the "winner" state (i.e. $f(w)=1$ ) and $|r\rangle$ be the uniform superposition of the remaining states i.e. $\frac{1}{\sqrt{N-1}} \sum_{x \neq w}|x\rangle$

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Both vectors yield 2-dimensional real vector space with orthonormal basis $\{|w\rangle,|r\rangle\}$

Also, uniform superposition $|\psi\rangle=H^{\otimes n}|0\rangle$, i.e. our starting state, rewritten as

$$
\frac{1}{\sqrt{N}}|w\rangle+\sqrt{\frac{N-1}{N}}|r\rangle
$$

## Setting a Geometric Stage pt. II

Last slide gives rise to


Goal is to rotate $|\psi\rangle$ so that it is as close as possible to $|w\rangle$

## Oracle and Inversion about the Mean, Geometrically

Also useful to revisit two operations under the light of the new vector space. Namely

- the oracle $\left(U_{f}\right)$
- and inversion about the mean $(2|\psi\rangle\langle\psi|-I)$


## Oracle and Inversion about the Mean, Geometrically

Also useful to revisit two operations under the light of the new vector space. Namely

- the oracle $\left(U_{f}\right)$
- and inversion about the mean $(2|\psi\rangle\langle\psi|-I)$

We will see that $(2|\psi\rangle\langle\psi|-I) U_{f}$ amounts to a counter-clockwise rotation of $\theta$ radians

## The Oracle pt. I

It is defined by

$$
\begin{cases}|x\rangle \mapsto|x\rangle & \\ \text { if } x \neq w \\ |x\rangle \mapsto-|x\rangle & \\ \text { otherwise }\end{cases}
$$

In particular for the basis $\{|w\rangle,|r\rangle\}$ we deduce

$$
\left\{\begin{array}{l}
|w\rangle \mapsto-|w\rangle \\
|r\rangle \mapsto|r\rangle
\end{array}\right.
$$

which corresponds to $2|r\rangle\langle r|-1$

## The Oracle pt. II

$(2|r\rangle\langle r|-\prime)(a|w\rangle+b|r\rangle)=-a|w\rangle+b|r\rangle$. Thus it corresponds to reflection about the $|r\rangle$-axis

$(2|r\rangle\langle r|-I)(\sin \alpha|w\rangle+\cos \alpha|r\rangle)=\sin -\alpha|w\rangle+\cos -\alpha|r\rangle$

## Inversion about the Mean

Analogously, $2|\psi\rangle\langle\psi|$ - I corresponds to reflection around the $|\psi\rangle$-axis

$(2|\psi\rangle\langle\psi|-I)(\sin -\alpha|w\rangle+\cos -\alpha|r\rangle)=\sin (\alpha+\theta)|w\rangle+\cos (\alpha+\theta)|r\rangle$

## Analysis of Grover Iterations

Let $G=(2|\psi\rangle\langle\psi|-I) U_{f}$. Then

$$
G(\sin \alpha|w\rangle+\cos \alpha|r\rangle)=\sin (\alpha+\theta)|w\rangle+\cos (\alpha+\theta)|r\rangle
$$

Therefore

$$
G^{k}(\sin \alpha|w\rangle+\cos \alpha|r\rangle)=\sin (\alpha+k \theta)|w\rangle+\cos (\alpha+k \theta)|r\rangle
$$

In particular

$$
G^{k}|\psi\rangle=\sin \left(\frac{\theta}{2}+k \theta\right)|w\rangle+\cos \left(\frac{\theta}{2}+k \theta\right)|r\rangle
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## Determining Grover's Performance

Recall: goal is to rotate $|\psi\rangle$ so that it is as close as possible to $|w\rangle$

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Formally, need to find integer $k$ s.t. $\sin \left(k \theta+\frac{\theta}{2}\right)=1$ i.e.

$$
k \theta+\frac{\theta}{2}=\frac{\pi}{2}
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Thus $k=$ c.i. $\left(\frac{\pi}{2 \theta}-\frac{1}{2}\right)$

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k \theta+\frac{\theta}{2}=\frac{\pi}{2}
$$

Thus $k=$ c.i. $\left(\frac{\pi}{2 \theta}-\frac{1}{2}\right)$
For very large $N$, we have $\frac{\theta}{2} \approx \frac{1}{\sqrt{N}}$ and therefore

$$
\begin{aligned}
& \frac{\pi}{2 \theta}-\frac{1}{2} \\
\approx & \frac{\pi}{\frac{4}{\sqrt{N}}}-\frac{1}{2} \\
= & \frac{\pi \sqrt{N}}{4}-\frac{1}{2}
\end{aligned}
$$

Thus Grover's algorithm has complexity $O(\sqrt{N})$

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## Grover's Problem Generalised to Multiple Solutions

The Problem
Take a function $f:\{0,1\}^{n} \rightarrow\{0,1\}$
There exist $M$ elements $x \in\{0,1\}^{n}$ such that $f(x)=1$
Discover one of such elements
Classically, need to evaluate $f\left(2^{n}-M\right)$ times in the worst case

## Grover's Problem Generalised to Multiple Solutions

## The Problem

Take a function $f:\{0,1\}^{n} \rightarrow\{0,1\}$
There exist $M$ elements $x \in\{0,1\}^{n}$ such that $f(x)=1$
Discover one of such elements
Classically, need to evaluate $f\left(2^{n}-M\right)$ times in the worst case
Quantumly, need to evaluate $f$ around $\sqrt{\frac{2^{n}}{M}}$ times

## Same Circuit



Main difference is that inversion of local phases will be applied to $M$ states, not necessarily one

## Back to the Geometrical Perspective

Let $|w\rangle$ be the uniform superposition of "winner" states i.e. $\frac{1}{\sqrt{M}} \sum_{x \text { a sol. }}|x\rangle$ and $|r\rangle$ be the uniform superposition of the remaining states i.e. $\frac{1}{\sqrt{N-M}} \sum_{x \text { not a sol. }}|x\rangle$

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Both vectors yield a 2-dimensional vector space with orthonormal basis $\{|w\rangle,|r\rangle\}$

Also, uniform superposition $|\psi\rangle$ can be rewritten as

$$
\sqrt{\frac{M}{N}}|w\rangle+\sqrt{\frac{N-M}{N}}|r\rangle
$$

## Back to the Geometrical Perspective

Last slide gives rise to


Goal is to rotate the vector to become as close as possible to $|w\rangle$

## Oracle and Inversion Revisited

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Oracle operation $2|r\rangle\langle r|-I$ still corresponds to a reflection about the $|r\rangle$-axis

Inversion about the mean $2|\psi\rangle\langle\psi|-I$ still corresponds to a reflection about the $|\psi\rangle$-axis

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Let $G=(2|\psi\rangle\langle\psi|-I) U_{f}$. Then

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Thus $k=$ c.i. $\left(\frac{\pi}{2 \theta}-\frac{1}{2}\right)$
When $M$ much smaller than $N$, we have $\frac{\theta}{2} \approx \sqrt{\frac{M}{N}}$ and therefore

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\begin{aligned}
& \frac{\pi}{2 \theta}-\frac{1}{2} \\
\approx & \frac{\pi}{4 \sqrt{\frac{M}{N}}}-\frac{1}{2} \\
= & \frac{\pi \sqrt{N}}{4 \sqrt{M}}-\frac{1}{2}
\end{aligned}
$$

Thus Grover's algorithm has complexity $O\left(\sqrt{\frac{N}{M}}\right)$

## Exercise

Let $N=4$ and $M=2$
What $n^{\circ}$ of Grover iterations would you choose?
What is the probability of succeeding with the chosen $n^{\circ}$ of iterations?

How to improve the probability of success?

## To Follow . . .

Grover's algorithm assumes that one knows the $n^{\circ}$ of solutions of the problem a priori

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In the following lectures we will see how to overcome such a limitation

