Contexts and tensorial strength

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Architecture and Calculi Course Unit

It is very useful to have two programs M, N in sequential composition $x \leftarrow M$; N that are able share contexts

In other words, it is 1 useful to have the following rule for sequential composition

$$\frac{\Gamma \vdash_{\mathsf{c}} M : \mathbb{A} \qquad \Gamma, x : \mathbb{A} \vdash_{\mathsf{c}} N : \mathbb{B}}{\Gamma \vdash_{\mathsf{c}} x \leftarrow M ; N : \mathbb{B}}$$

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This would allow us to solve the previous exercise quite easily

$$f : \mathbb{A} \to \mathbb{A}, x : \mathbb{A} \vdash_{c} y \leftarrow f(x); f(y) : \mathbb{A}$$

The natural way of interpreting the rule would be

$$\frac{\llbracket \Gamma \vdash_{c} M : \mathbb{A} \rrbracket = f \qquad \llbracket \Gamma, x : \mathbb{A} \vdash_{c} N : \mathbb{B} \rrbracket = g}{\llbracket \Gamma \vdash_{c} x \leftarrow M ; N : \mathbb{B} \rrbracket = g^{\star} \cdot \langle \mathsf{id}, f \rangle}$$

but $\langle \mathsf{id}, f \rangle : \llbracket \Gamma \rrbracket \longrightarrow \llbracket \Gamma \rrbracket \times T \llbracket \mathbb{A} \rrbracket$ and $g^* : T(\llbracket \Gamma \rrbracket \times \llbracket \mathbb{A} \rrbracket) \longrightarrow T \llbracket \mathbb{B} \rrbracket$

Thus we need to find a suitable function

$$\operatorname{str}: \llbracket \Gamma \rrbracket \times T \llbracket \mathbb{A} \rrbracket \longrightarrow T (\llbracket \Gamma \rrbracket \times \llbracket \mathbb{A} \rrbracket)$$

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There is a natural way of doing this

Tensorial strength

For every monad T and function $f: X \to Y$ we can build a function

 $Tf = (\eta \cdot f)^* : TX \to TY$

Note also that for every $x \in X$ we can define

$$\mathsf{id}_x: Y \to X \times Y, \quad y \mapsto (x, y)$$

From these we define the so-called strength of T

$$\operatorname{str}: X \times TY \to T(X \times Y), \quad (x,t) \mapsto (T\operatorname{id}_{x})(t)$$

Finally,

$$\frac{\llbracket \Gamma \vdash_{c} M : \mathbb{A} \rrbracket = f \qquad \llbracket \Gamma, x : \mathbb{A} \vdash_{c} N : \mathbb{B} \rrbracket = g}{\llbracket \Gamma \vdash_{c} x \leftarrow M ; N : \mathbb{B} \rrbracket = g^{\star} \cdot \operatorname{str} \cdot \langle \operatorname{id}, f \rangle}$$

Exercises

Given an explicit definition for the tensorial strength of

- the monad of exceptions,
- the monad of durations

Consider the λ -term,

$$f : \mathbb{A} \to \mathbb{A}, x : \mathbb{A} \vdash_{c} y \leftarrow f(x); f(y) : \mathbb{A}$$

What is its execution time when,

f is given by $(v \mapsto (1, v))$

Semantics of effectul $\lambda\text{-calculus}$ with shared contexts

$$\begin{aligned} \begin{array}{l} x_{i} : \mathbb{A} \in \Gamma \\ \hline \llbracket \Gamma \vdash x_{i} \rrbracket = \pi_{i} \\ \hline \llbracket \Gamma \vdash x_{i} \end{matrix} = \pi_{i} \\ \hline \llbracket \Gamma \vdash x_{i} \end{matrix} = \pi_{i} \\ \hline \llbracket \Gamma \vdash x_{i} \end{matrix} = \pi_{i} \\ \hline \llbracket \Gamma \vdash x_{i} \end{matrix} = \pi_{i} \\ \hline \llbracket \Gamma \vdash x_{i} \end{matrix} = \pi_{i} \\ \hline \llbracket \Gamma \vdash x_{i} \end{matrix} = \pi_{i} \\ \hline \llbracket \Gamma \vdash x_{i} \end{matrix} = \pi_{i} \\ \hline \llbracket \Gamma \vdash x_{i} \end{matrix} = \pi_{i} \\ \hline \llbracket \Gamma \vdash x_{i} \end{matrix} = \pi_{i} \\ \hline \llbracket \Gamma \vdash x_{i} \end{matrix} = \pi_{i} \\ \hline \llbracket \Gamma \vdash x_{i} \end{matrix} = \pi_{i} \\ \hline \llbracket \Gamma \vdash x_{i} \end{matrix} = \pi_{i} \\ \hline \llbracket \Gamma \vdash x_{i} \end{matrix} = \pi_{i} \\ \hline \llbracket \Gamma \vdash x_{i} \end{matrix} = \pi_{i} \\ \hline \llbracket \Gamma \vdash x_{i} \end{matrix} = \pi_{i} \\ \hline \llbracket \Gamma \vdash x_{i} \end{matrix} = \pi_{i} \\ \hline \llbracket \Gamma \vdash x_{i} \end{matrix} = \pi_{i} \\ \hline \llbracket \Gamma \vdash x_{i} \end{matrix} = \pi_{i} \\ \hline \llbracket \Gamma \vdash x_{i} \end{matrix} = \pi_{i} \\ \hline \blacksquare T \vdash x_{i}$$