Luís Soares Barbosa









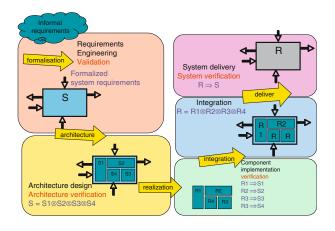
Architecture & Calculi Course Unit

Universidade do Minho



Software development as one of the most complex but at the same time most effective tasks in the engineering of innovative applications:

- Software drives innovation in many application domains
- Appropriate software provides engineering solutions that can calculate results, communicate messages, control devices, animate and reason about all kinds of information
- Actually software is becoming everyware ...



Software Engineering (illustration from [Broy, 2007])



So, ... yet another module in the MFES profile?

Models and analysis of reactive systems

characterised by

- a methodological shift: an architectural perspective (compositionality; interaction; focus on observable behaviour)
- a focus: on reactive systems nondeterministic, probabilistic, timed, cyber-physical

Reactive system

system that computes by reacting to stimuli from its environment along its overall computation

- in contrast to sequential systems whose meaning is defined by the results of finite computations, the behaviour of reactive systems is mainly determined by interaction and mobility of non-terminating processes, evolving concurrently.
- observation = interaction
- behaviour = a structured record of interactions



Definition

A LTS over a set N of names is a tuple $\langle S, N, \downarrow, \longrightarrow \rangle$ where

- $S = \{s_0, s_1, s_2, ...\}$ is a set of states
- $\downarrow \subseteq S$ is the set of terminating or final states

$$\downarrow s \equiv s \in \downarrow$$

• $\longrightarrow \subseteq S \times N \times S$ is the transition relation, often given as an N-indexed family of binary relations

$$s \stackrel{a}{\longrightarrow} s' \equiv \langle s', a, s \rangle \in \longrightarrow$$

Morphism

A morphism relating two LTS over N, $\langle S, N, \downarrow, \longrightarrow \rangle$ and $\langle S', N, \downarrow', \longrightarrow' \rangle$, is a function $h: S \longrightarrow S'$ st

$$s \stackrel{a}{\longrightarrow} s' \quad \Rightarrow \quad h s \stackrel{a}{\longrightarrow}' h s'$$

 $s \downarrow \quad \Rightarrow \quad h s \downarrow'$

morphisms preserve transitions and termination

System

Given a LTS $\langle S, N, \downarrow, \longrightarrow \rangle$, each state $s \in S$ determines a system over all states reachable from s and the corresponding restrictions of \longrightarrow and \downarrow .

LTS classification

- deterministic
- non deterministic
- finite
- finitely branching
- image finite
- •

Reachability

Definition

The reachability relation, $\longrightarrow^* \subseteq S \times N^* \times S$, is defined inductively

- $s \xrightarrow{\epsilon}^* s$ for each $s \in S$, where $\epsilon \in N^*$ denotes the empty word;
- if $s \xrightarrow{a} s''$ and $s'' \xrightarrow{\sigma} s'$ then $s \xrightarrow{a\sigma} s'$, for $a \in N, \sigma \in N^*$

Reachable state

 $t \in S$ is reachable from $s \in S$ iff there is a word $\sigma \in N^*$ st $s \xrightarrow{\sigma}^* t$

Alternative characterization (coalgebraic)

A morphism $h: \langle S, \mathsf{next} \rangle \longrightarrow \langle S', \mathsf{next}' \rangle$ is a function $h: S \longrightarrow S'$ st the following diagram commutes

$$S \times N \xrightarrow{\text{next}} \mathcal{P}S$$

$$h \times id \downarrow \qquad \qquad \downarrow \mathcal{P}h$$

$$S' \times N \xrightarrow{\text{next}'} \mathcal{P}S'$$

i.e.,

$$\mathfrak{P}h \cdot \mathsf{next} = \mathsf{next}' \cdot (h \times id)$$

or, going pointwise,

$$\{h \mid x \mid x \in \text{next } \langle s, a \rangle\} = \text{next'} \langle h \mid s, a \rangle$$

Alternative characterization (coalgebraic)

A morphism $h: \langle S, \text{next} \rangle \longrightarrow \langle S', \text{next}' \rangle$

• preseves transitions:

$$s' \in \text{next } \langle s, a \rangle \Rightarrow h \ s' \in \text{next'} \ \langle h \ s, a \rangle$$

reflects transitions:

$$r' \in \mathsf{next}' \langle h \, s, a \rangle \Rightarrow \langle \exists \, s' \in S : s' \in \mathsf{next} \langle s, a \rangle : r' = h \, s' \rangle$$

(why?)

Comparison

• Both definitions coincide at the object level:

$$\langle s, a, s' \rangle \in T \equiv s' \in \text{next } \langle s, a \rangle$$

 Wrt morphisms, the relational definition is more general, corresponding, in coalgebraic terms to

$$\mathcal{P}h \cdot \text{next} \subseteq \text{next}' \cdot (h \times id)$$

Looking for suitable notions of equivalence of behaviours

Intuition

Two LTS should be equivalent if they cannot be distinguished by interacting with them.

Equality of functional behaviour

is not preserved by parallel composition: non compositional semantics, cf,

$$x:=4$$
; $x:=x+1$ and $x:=5$

Graph isomorphism

is too strong (why?)

Trace

Definition

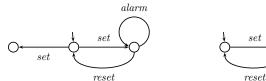
Let $T = \langle S, N, \longrightarrow \rangle$ be a labelled transition system. The set of traces Tr(s), for $s \in S$ is the minimal set satisfying

- (1) $\epsilon \in \mathsf{Tr}(s)$
- (3) $a\sigma \in \mathsf{Tr}(s) \Rightarrow \langle \exists \ s' : \ s' \in S : \ s \stackrel{a}{\longrightarrow} s' \land \sigma \in \mathsf{Tr}(s') \rangle$

Definition

Two states s, r are trace equivalent iff Tr(s) = Tr(r)(i.e. they can perform the same finite sequences of transitions)

Example



Trace equivalence applies when one can neither interact with a system, nor distinguish a slow system from one that has come to a stand still.

alarm

set

Simulation

the quest for a behavioural equality: able to identify states that cannot be distinguished by any realistic form of observation

Simulation

A state q simulates another state p if every transition from q is corresponded by a transition from p and this capacity is kept along the whole life of the system to which state space q belongs to.

Simulation

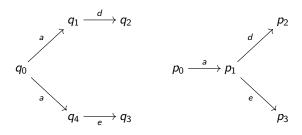
Definition

Given $\langle S_1, N, \longrightarrow_1 \rangle$ and $\langle S_2, N, \longrightarrow_2 \rangle$ over N, relation $R \subseteq S_1 \times S_2$ is a simulation iff, for all $\langle p, q \rangle \in R$ and $a \in N$,

(2)
$$p \xrightarrow{a}_1 p' \Rightarrow \langle \exists \ q' : \ q' \in S_2 : \ q \xrightarrow{a}_2 \ q' \land \langle p', q' \rangle \in R \rangle$$

$$\begin{array}{ccc}
p & R & q & \Rightarrow & q \\
\downarrow a & & \downarrow \\
p' & & p' & R & q'
\end{array}$$

Example



$$q_0 \lesssim p_0$$
 cf. $\{\langle q_0, p_0 \rangle, \langle q_1, p_1 \rangle, \langle q_4, p_1 \rangle, \langle q_2, p_2 \rangle, \langle q_3, p_3 \rangle\}$

Similarity

Definition

```
p \lesssim q \equiv \langle \exists R :: R \text{ is a simulation and } \langle p, q \rangle \in R \rangle
```

Lemma

The similarity relation is a preorder (i.e. reflexive and transitive)

Bisimulation

Definition

Given $\langle S_1, N, \longrightarrow_1 \rangle$ and $\langle S_2, N, \longrightarrow_2 \rangle$ over N, relation $R \subseteq S_1 \times S_2$ is a bisimulation iff both R and its converse R° are simulations. I.e. whenever $\langle p, q \rangle \in R$ and $a \in N$,

$$(1) \ p \stackrel{a}{\longrightarrow}_1 p' \ \Rightarrow \ \langle \exists \ q' \ : \ q' \in S_2 : \ q \stackrel{a}{\longrightarrow}_2 q' \land \langle p', q' \rangle \in R \rangle$$

(2)
$$q \xrightarrow{a}_2 q' \Rightarrow \langle \exists p' : p' \in S_1 : p \xrightarrow{a}_1 p' \land \langle p', q' \rangle \in R \rangle$$

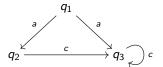
Bisimulation

The Game characterization

Two players R and I discuss whether the transition structures are mutually corresponding

- R starts by chosing a transition
- I replies trying to match it
- if I succeeds, R plays again
- R wins if I fails to find a corresponding match
- I wins if it replies to all moves from R and the game is in a configuration where all states have been visited or R can't move further. In this case is said that I has a wining strategy

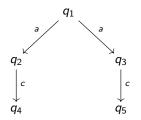
Examples

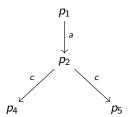


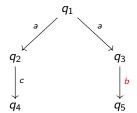
$$q_1 \xrightarrow{a} q_2 \xrightarrow{a} q_3 \xrightarrow{a} \cdots$$

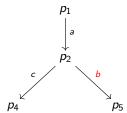
$$h \bigcirc a$$

Examples









- Follows a \forall , \exists pattern: p in all its transitions challenge q which is called to find a matchh to each of those (and conversely)
- Tighter correspondence with transitions
- Based on the information that the transitions convey, rather than on the shape of the LTS
- Local checks on states
- Lack of hierarchy on the pairs of the bisimulation (no temporal order on the checks is required)

which means bisimilarity can be used to reason about infinite or circular behaviours.

Compare the definition of bisimilarity with

$$p == q$$
 if, for all $a \in N$

$$(1) \ p \stackrel{a}{\longrightarrow}_1 p' \ \Rightarrow \ \langle \exists \ q' \ : \ q' \in S_2 : \ q \stackrel{a}{\longrightarrow}_2 q' \ \wedge \ p' == q' \rangle$$

(2)
$$q \xrightarrow{a}_2 q' \Rightarrow \langle \exists p' : p' \in S_1 : p \xrightarrow{a}_1 p' \land p' == q' \rangle$$

$$p == q$$
 if, for all $a \in N$

(1)
$$p \downarrow_1 \Leftrightarrow q \downarrow_2$$

$$(2.1) \ p \xrightarrow{a}_1 p' \Rightarrow \langle \exists \ q' : \ q' \in S_2 : \ q \xrightarrow{a}_2 q' \land p' == q' \rangle$$

$$(2.1) \ q \xrightarrow{a}_2 q' \Rightarrow \langle \exists \ p' : \ p' \in S_1 : \ p \xrightarrow{a}_1 p' \land p' == q' \rangle$$

- The meaning of == on the pair $\langle p, q \rangle$ requires having already established the meaning of == on the derivatives
- ... therefore the definition is ill-founded if the state space reachable from $\langle p, q \rangle$ is infinite or contain loops
- ... this is a local but inherently inductive definition (to revisit later)

Proof method

To prove that two behaviours are bisimilar, find a bisimulation containing them ...

- ... impredicative character
- coinductive vs inductive definition.

Definition

$$p \sim q \equiv \langle \exists R :: R \text{ is a bisimulation and } \langle p, q \rangle \in R \rangle$$

Lemma

- 1. The identity relation *id* is a bisimulation
- 2. The empty relation \perp is a bisimulation
- 3. The converse R° of a bisimulation is a bisimulation
- 4. The composition $S \cdot R$ of two bisimulations S and R is a bisimulation
- 5. The $\bigcup_{i \in I} R_i$ of a family of bisimulations $\{R_i \mid i \in I\}$ is a bisimulation

Lemma

The bisimilarity relation is an equivalence relation (i.e. reflexive, symmetric and transitive)

Lemma

The class of all bisimulations between two LTS has the structure of a complete lattice, ordered by set inclusion, whose top is the bisimilarity relation \sim .

Lemma

In a deterministic labelled transition system, two states are bisimilar iff they are trace equivalent, i.e.,

$$s \sim s' \Leftrightarrow \mathsf{Tr}(s) = \mathsf{Tr}(s')$$

Hint: define a relation R as

$$\langle x, y \rangle \in R \Leftrightarrow \mathsf{Tr}(x) = \mathsf{Tr}(y)$$

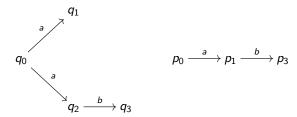
and show R is a bisimulation.

Warning

The bisimilarity relation \sim is not the symmetric closure of \lesssim

Example

$$q_0 \lesssim p_0, \ p_0 \lesssim q_0 \quad \text{but} \quad p_0 \not\sim q_0$$



Notes

Similarity as the greatest simulation

$$\lesssim \ \widehat{=} \ \bigcup \{S \mid S \text{ is a simulation}\}\$$

Bisimilarity as the greatest bisimulation

$$\sim \ \widehat{=} \ \bigcup \{S \mid S \text{ is a bisimulation}\}\$$

Automata

Back to old friends?

automaton behaviour \equiv accepted language

Recall that finite automata recognize regular languages, i.e. generated by

- $L_1 + L_2 \stackrel{\frown}{=} L_1 \cup L_2$ (union)
- $L_1 \cdot L_2 = \{st \mid s \in L_1, t \in L_2\}$ (concatenation)
- $L^* = \{\epsilon\} \cup L \cup (L \cdot L) \cup (L \cdot L \cdot L) \cup ...$ (iteration)

Automata

There is a syntax to specify such languages:

$$E ::= \epsilon \mid a \mid E + E \mid EE \mid E^*$$

where $a \in \Sigma$.

- which regular expression specifies {a, bc}?
- and {ca, cb}?

and an algebra of regular expressions:

$$(E_1 + E_2) + E_3 = E_1 + (E_2 + E_3)$$

 $(E_1 + E_2) E_3 = E_1 E_3 + E_2 E_3$
 $E_1 (E_2 E_1)^* = (E_1 E_2)^* E_1$

Automata

There is a syntax to specify such languages:

$$E ::= \epsilon \mid a \mid E + E \mid EE \mid E^*$$

where $a \in \Sigma$.

- which regular expression specifies {a, bc}?
- and {ca, cb}?

and an algebra of regular expressions:

$$(E_1 + E_2) + E_3 = E_1 + (E_2 + E_3)$$

 $(E_1 + E_2) E_3 = E_1 E_3 + E_2 E_3$
 $E_1 (E_2 E_1)^* = (E_1 E_2)^* E_1$

... need more general models and theories:

- Several interaction points (≠ functions)
- Need to distinguish normal from anomalous termination (eg deadlock)
- Nondeterminisim should be taken seriously: the reactive character
 of systems entail that not only the generated language is important,
 but also the states traversed during an execution of the automata.
- New systems from old: going compositional