Introduction to labelled transition systems

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Reactive systems

Reactive system

system that computes by reacting to stimuli from its environment along its overall computation

- in contrast to sequential systems whose meaning is defined by the results of finite computations, the behaviour of reactive systems is mainly determined by interaction and mobility of non-terminating processes, evolving concurrently.
- observation \equiv interaction
- behaviour \equiv a structured record of interactions

Labelled Transition System

Definition

A LTS over a set N of names is a tuple $\langle S, N, \longrightarrow \rangle$ where

- $S = \{s_0, s_1, s_2, ...\}$ is a set of states
- $\longrightarrow \subseteq S \times N \times S$ is the transition relation, often given as an *N*-indexed family of binary relations

$$s \stackrel{a}{\longrightarrow} s' \equiv \langle s, a, s' \rangle \in \longrightarrow$$

Labelled Transition System

System

Given a LTS (S, N, \rightarrow) , each state $s \in S$ determines a system over all states reachable from s and the corresponding restriction of \rightarrow .

LTS classification

- deterministic
- non deterministic
- finite
- finitely branching
- image finite



Reachability

Definition

The reachability relation, $\longrightarrow^* \subseteq S \times N^* \times S$, is defined inductively

• $s \xrightarrow{\epsilon} s$ for each $s \in S$, where $\epsilon \in N^*$ denotes the empty word;

• if
$$s \xrightarrow{a} s''$$
 and $s'' \xrightarrow{\sigma}^* s'$ then $s \xrightarrow{a\sigma}^* s'$, for $a \in N, \sigma \in N^*$

Reachable state

 $t \in S$ is reachable from $s \in S$ iff there is a word $\sigma \in N^*$ st $s \xrightarrow{\sigma}^* t$

An alternative characterisation

Coalgebraic characterization (morphism)

A morphism $h: \langle S, \text{next} \rangle \longrightarrow \langle S', \text{next'} \rangle$ is a function $h: S \longrightarrow S'$ st the following diagram commutes



i.e.,

$$\mathcal{P}h \cdot \text{next} = \text{next}' \cdot (h \times \text{id})$$

or, going pointwise,

$$\{h \ x \mid x \in \text{next} \ \langle s, a \rangle\} = \text{next}' \ \langle h \ s, a \rangle$$

An alternative characterisation

Coalgebraic characterization (morphism)

A morphism $h: \langle S, \mathsf{next} \rangle \longrightarrow \langle S', \mathsf{next'} \rangle$

preseves transitions:

$$s' \in \mathsf{next} \langle s, a
angle \Rightarrow h \ s' \in \mathsf{next}' \ \langle h \ s, a
angle$$

reflects transitions:

$$r' \in \operatorname{next}' \langle h \ s, a \rangle \Rightarrow \langle \exists \ s' \in S \ : \ s' \in \operatorname{next} \langle s, a \rangle : \ r' = h \ s' \rangle$$

(why?)

Both definitions coincide at the object level:

$$\langle s, a, s'
angle \in T \ \equiv \ s' \in \mathsf{next} \ \langle s, a
angle$$

• Wrt morphisms, the relational definition is more general, corresponding, in coalgebraic terms to

$$\mathcal{P}h \cdot \text{next} \subseteq \text{next}' \cdot (h \times \text{id})$$

How can these notions of morphism be used to compare LTS?

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How can these notions of morphism be used to compare LTS?

Process algebras

CCS - Syntax

$$\mathcal{P} \ni \mathcal{P}, \mathcal{Q} ::= \mathcal{K} \mid \alpha.\mathcal{P} \mid \sum_{i \in I} \mathcal{P}_i \mid \mathcal{P}[f] \mid \mathcal{P}|\mathcal{Q} \mid \mathcal{P} \setminus \mathcal{L}$$

where

- $\alpha \in \mathbf{N} \cup \overline{\mathbf{N}} \cup \{\tau\}$ is an action
- K s a collection of process names or process contants
- I is an indexing set
- $L \subseteq N \cup \overline{N}$ is a set of labels
- f is a function that renames actions s.t. $f(\tau) = \tau$ and $f(\overline{a}) = \overline{f(a)}$
- notation:

$$\begin{aligned} \mathbf{0} &= \sum_{i \in \emptyset} P_i \\ P_1 + P_2 &= \sum_{i \in \{1,2\}} P_i \\ [f] &= [b_1/a_1, \dots, b_n/a_n] \end{aligned}$$

Process algebras

Syntax

$$\mathcal{P} \ni \mathcal{P}, \mathcal{Q} ::= \mathcal{K} \mid \alpha.\mathcal{P} \mid \sum_{i \in I} \mathcal{P}_i \mid \mathcal{P}[f] \mid \mathcal{P}|\mathcal{Q} \mid \mathcal{P} \setminus \mathcal{L}$$

Exercise: Which are syntactically correct?

a.b.A + B	(1)
$(a.0+\overline{a}.A)ackslash\{a,b\}$	(2)
$(a.0+\overline{a}.A)ackslash\{a, au\}$	(3)
a.B + [a/b]	(4)
au. $ au$. $B + 0$	(5)
(a.B+b.B)[a/a,b/ au]	(6)

$(a.B + \tau.B)[a/b, a/a]$	(7)
$(a.b.A + \overline{a}.0) B$	(8)
$(a.b.A + \overline{a}.0).B$	(9)
$(a.b.A + \overline{a}.0) + B$	(10)
(0 0) + 0	(11)

CCS semantics - building an LTS



Exercise: Draw the LTS's

CM = coin.coffee. CM $CS = \overline{\text{pub.coin.coffee.} CS}$ $SmUni = (CM|CS) \setminus \{\text{coin, coffee}\}$

CCS semantics - building an LTS



Exercise: Draw the LTS's

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mCRL2

http://mcrl2.org

- Formal specification language with an associated toolset
- Used for modelling, validating and verifying concurrent systems and protocols

mCRL2

Syntax (by example)

$$\begin{array}{l} a.P \rightarrow a.P \\ P_1 + P_2 \rightarrow \text{P1 + P2} \\ P \setminus L \rightarrow \textit{block}(\text{L},\text{P}) \\ P[f] \rightarrow \textit{rename}(f,\text{P}) \\ a.P|\overline{a}.Q \rightarrow \textit{hide}(\{a\},\textit{comm}(\{a1|a2\rightarrow a\},a1.P||a2.P))) \\ (a.P|\overline{a}.Q) \setminus \{a\} \rightarrow \textit{hide}(\{a\},\textit{block}(\{a1,a2\},\textit{comm}(\{a1|a2\rightarrow a\},a1.P||a2.Q))) \end{array}$$

mCRL2

```
act
  coin, coin', coinCom,
  coffee, coffee', coffeeCom, pub';
proc
  CM = coin.coffee'.CM;
  CS = pub'.coin'.coffee.CS;
  CMCS = CM || CS;
  SmUni = hide({coffeeCom, coinCom},
          block({coffee,coffee',coin,coin'},
          comm ({coffee|coffee' \rightarrow coffeeCom,
                 coin|coin' \rightarrow coinCom\},
          CMCS ))):
init
  SmUni;
```

LTS – Basic definitions	Process algebra	mCRL2	Data

Example

Clock

act	set, alarm,	reset;
proc	P = set.R R = reset.P	+ alarm.R
init	Р	

Example

A refined clock act set:N, alarm, reset, tick; proc P = (sum n:N . set(n).R(n)) + tick.P R(n:N) = reset.P + ((n == 0) -> alarm.R(0) <> tick.R(n-1)) init P

$\|$ = interleaving + synchronization

- modelling principle: interaction is the key element in software design
- modelling principle: (distributed, reactive) architectures are configurations of communicating black boxes
- mCRL2: supports flexible synchronization discipline (≠ CCS)

$$p ::= \cdots \mid p \parallel p \mid p \mid p \mid p \parallel p$$



- parallel p || q: interleaves and synchronises the actions of both processes.
- synchronisation p | q: synchronises the first actions of p and q and combines the remainder of p with q with ||, cf axiom:

$$(a.p) \mid (b.q) \sim (a \mid b) . (p \parallel q)$$

• left merge p || q: executes a first action of p and thereafter combines the remainder of p with q with ||.

A semantic parentesis

Lemma: There is no sound and complete finite axiomatisation for this process algebra with || modulo bisimilarity [F. Moller, 1990].

Solution: combine two auxiliar operators:

- left merge: ||
- synchronous product: |

such that

 $p \parallel t \sim (p \parallel t + t \parallel p) + p \mid t$

Interaction

Communication $\Gamma_{C}(p)$ (com)

• applies a communication function *C* forcing action synchronization and renaming to a new action:

 $a_1 \mid \cdots \mid a_n \rightarrow c$

data parameters are retained in action c, e.g.

$$\begin{split} & \Gamma_{\{a|b\to c\}}(a(8) \mid b(8)) = c(8) \\ & \Gamma_{\{a|b\to c\}}(a(12) \mid b(8)) = a(12) \mid b(8) \\ & \Gamma_{\{a|b\to c\}}(a(8) \mid a(12) \mid b(8)) = a(12) \mid c(8) \end{split}$$

• left hand-sides in C must be disjoint: e.g., $\{a \mid b \rightarrow c, a \mid d \rightarrow j\}$ is not allowed

Interface control

Restriction: $\nabla_B(p)$ (allow)

- specifies which multiactions from a non-empty multiset of action names are allowed to occur
- disregards the data parameters of the multiactions

 $\nabla_{\{d,b|c\}}(d(12) + a(8) + (b(false, 4) \mid c)) = d(12) + (b(false, 4) \mid c)$

• au is always allowed to occur

Discuss: $\nabla_{\{x,y\}}(\Gamma_{\{a|c->x,b|d->y\}}(a.b \parallel c.d))$

Interface control

Block: $\partial_B(p)$ (block)

- specifies which multiactions from a set of action names are not allowed to occur
- disregards the data parameters of the multiactions

$$\partial_{\{b\}}(d(12) + a(8) + (b(false, 4) | c)) = d(12) + a(8)$$

- the effect is that of renaming to $\boldsymbol{\delta}$
- τ cannot be blocked

Interaction



LTS – Basic definitions	Process algebra	mCRL2	Data

Interaction

Enforce communication

- $\nabla_{\{c\}}(\Gamma_{\{a|b\to c\}}(p))$ $\partial_{\{a,b\}}(\Gamma_{\{a|b\to c\}}(p))$

Interface control

Renaming $\rho_M(p)$ (rename)

- renames actions in p according to a mapping M
- also disregards the data parameters, but when a renaming is applied the data parameters are retained:

$$\partial_{\{d \to h\}}(d(12) + s(8) \mid d(false) + d.a.d(7))$$

= $h(12) + s(8) \mid h(false) + h.a.h(7)$

• τ and δ cannot be renamed

Interface control

Hiding $\tau_H(p)$ (hide)

- hides (or renames to \(\tau\)) all actions with an action name in H in all multiactions of p. renames actions in p according to a mapping M
- disregards the data parameters

$$egin{aligned} & \pi_{\{d\}}(d(12) + s(8) \mid d(\mathit{false}) + h.a.d(7)) \ &= & au + s(8) \mid au + h.a. au \ &= & au + s(8) + h.a. au \end{aligned}$$

Example

New buffers from old

```
act inn,outt,ia,ib,oa,ob,c : Bool;
```

```
proc BufferS = sum n: Bool.inn(n).outt(n).BufferS;
```

```
BufferA = rename({inn -> ia, outt -> oa}, BufferS);
BufferB = rename({inn -> ib, outt -> ob}, BufferS);
```

```
S = allow({ia,ob,c}, comm({oa|ib -> c}, BufferA || BufferB));
```

```
init hide({c}, S);
```

- Equalities: equality, inequality, conditional (if(-,-,))
- Basic types: booleans, naturals, reals, integers, ... with the usual operators
- Sets, multisets, sequences ... with the usual operators
- Function definition, including the λ -notation
- Inductive types: as in

sort BTree = struct leaf(Pos) | node(BTree, BTree)

Signatures and definitions

Sorts, functions, constants, variables ...

sort S, A;

- cons s,t:S, b:set(A);
- map f: S x S -> A;
 - c: A;
- var x:S;

eqn f(x,s) = s;

Signatures and definitions

A full functional language ...

sort LTree = struct leaf(Pos) | node(LTree, LTree);

map flatten: LTree -> List(Pos);

var n:Pos, t,r:LTree;

eqn flatten(leaf(n)) = [n];
flatten(node(t,r)) = flatten(t) ++ flatten(r);

Processes with data

Why?

- Precise modeling of real-life systems
- Data allows for finite specifications of infinite systems

How?

- data and processes parametrized
- summation over data types: $\sum_{n:N} s(n)$
- processes conditional on data: $b \rightarrow p \diamond q$

Examples

A counter

```
act up, down;
setcounter:Pos;
```

init Ctr(345);

Examples

A dynamic binary tree

- act left,right;
- map N:Pos;
- eqn N = 512;
- proc X(n:Pos)=(n<=N)->(left.X(2*n)+right.X(2*n+1))<>delta;

init X(1);

mCRL2 toolset overview



- mCRL2 tutorial: Modelling part -